

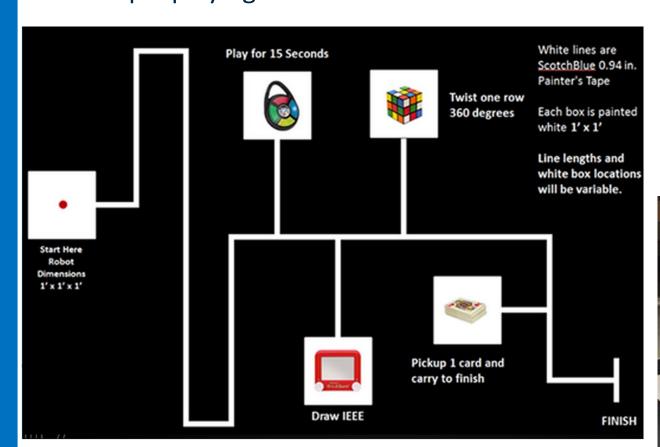
Southeast Con 1 B



BACKGROUND/INFO

Robot must autonomously follow a white line course and complete the following tasks:

- Detect a red LED turning off
- Play Simon Says for 15 seconds
- Write IEEE on Etch-A-Sketch
- Turn a face of a Rubik's cube 180 degrees
- Pick up a playing card from a deck & cross finish



TEAM MEMBERS

Ivan Vargas: EE, Equipment Technician

-Webpage & Programming Editor, 3D Models

Lorenzo Smith: EE, Project Manager

-Power & Wire Management, Chassis

Chelsea Ogle: EE, Secretary

-Drive System, MATLAB, Signal Processing

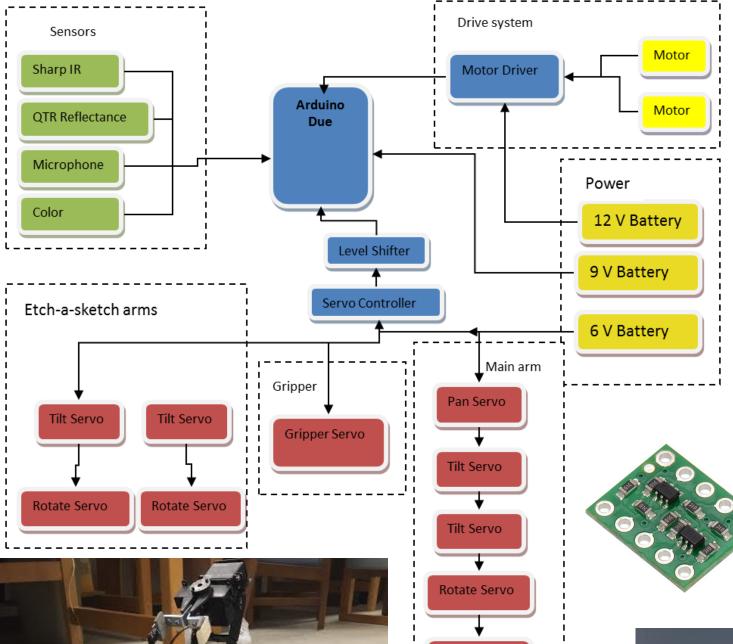
Louis Cooper: EE, Treasurer, Robot Mechanic

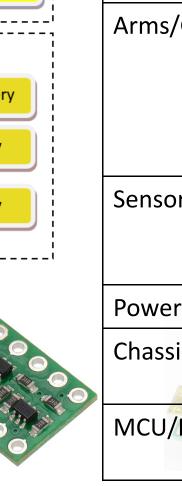
-Robot Technician, Game Specialist

Evan Marshall: CE, Programming Manager

- Sensors, Chassis

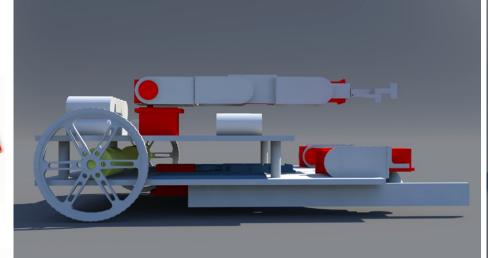
TOP-LEVEL SYSTEM DIAGRAM

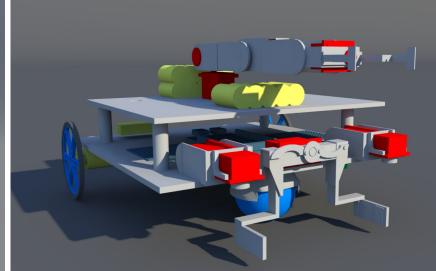




DESIGN SPCIFICATIONS

System	Components
Drive System	2 DC Brushed Motors, two 90mm Wheels with Silicone Tires
Arms/Grippers	Main Arm, Chassis Gripper, Etch-A-Sketch Grippers, Level Shifter, [Arms/Grippers custom made of Standard and Continuous Rotation Servos with Aluminum Brackets]
Sensors	QTR 8RC Sensors (line following), Analog Distance Sensor, Electret Microphone Amplifier
Power	6V, 9V, 12V NiMH Rechargeable Batteries
Chassis	2 Layers of High-density Polyethylene, Brass Columns
MCU/Integration	Arduino Due, Maestro Servo Controller, MC33926 Motor Driver Shield





SCHEDULE SUMMARY

Tasks	Completed by	
Drive System	1/17	
Chassis, Rubik's Cube	2/10	
Playing Card	2/20	
Distance Sensing, LED Activation	2/25	
Etch-A-Sketch	3/9	
Simon, Line Following	3/20	

TEST PLAN SUMMARY

TEST	RESULT
Demo code	Pass
Line following	Pass
Detect start LED	Pass
Turn Rubik's cube face 180°	Pass
Write IEEE on Etch-A-Sketch	Pass
Pick up playing card	Pass
Press all colors on Simon	Pass

BUDGET ESTIMATE

EXPENSES	PRICE
Microcontroller	\$80.00
Sensors	\$42.05
Wheels and Motors	\$118.89
Chassis	\$22.69
Arms, Grippers, Servos	\$172.24
Batteries and Charger	\$60.40
Miscellaneous	\$125
Total Cost of Project	\$621.26
Budget Provided	\$750.00