

### Miniature Modular Rack Launcher Combo



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## **Problem Statement**

- Design and develop a Bomb Rack Unit (BRU) that is attached to the Tigershark UAV capable of housing and launching a cylindrical payload.
- BRU must contain an electrical interface that allows the user to go through a safety sequence before the payload is released
- Provide budget analysis for MMRLC
- Prototype and fit check

### **Tigershark UAV Platform**

#### Specifications:

- Wing span 21 feet
- Propulsion 372cc two stroke
- 20 gallon fuel tank
- Empty airframe weight 150 lbs.
- Gross take off weight 300 lbs.
- Payload capacity 50 lbs.
- One hard-point location per wing for launcher attachment





Tolerance +/- 0.05"

### Constraints

- BRU must not exceed 5 lbs.
- Capable of holding a payload that is 10lbs
- Operation in temperature range -20 to 60 degrees C and during rain exposure
- Retain payload during aircraft maneuvers up to 2GS lateral load and 1G landing shock.



Weight = 10lbs Tolerance +/- 0.125"

# Latch System

- Hold payload in place during aircraft maneuvers
  - 2Gs lateral load
  - 1G Landing shock
- Integrated with safety system that prevents hooks from opening before "ARM" signal is received.
- Integrated into electrical interface allowing the hooks to swing away during the "RELEASE" command











### **Decision Matrix**

		Designs										
		1		2		3		4		5		
Specifications	Weight	Score	Weight	Score	Weight	Score	Weight	Score	Weight	Score	Weight	
Compactness	0.1	2	0.2	3	0.3	3	0.3	5	0.5	5	0.5	
Weight	0.25	4	1	2	0.5	5	1.25	5	1.25	5	1.25	
Strength	0.15	3	0.45	4	0.6	3	0.45	4	0.6	4	0.6	
Durability	0.1	3	0.4	4	0.4	2	0.2	4	0.4	4	0.4	
Operational Speed	0.4	5	2	3	1.2	2	0.8	3	1.2	5	2	
Total		4	4.05		3		3		3.95		4.75	

# Mechanical Safety System

- Moves to allow the hook to open when the system is put in "Armed" mode
- Uses a servomotor to achieve this motion

#### **Constraints:**

- Safety pins that mechanically inhibit launching mechanisms during ground procedures
  - Pins labeled with red "Remove Before Flight" flags
- Safety feature that interrupts launch mechanism until "ARM" command is received from the aircraft.
- Launcher shall eject payload when "RELEASE" command is received from the aircraft













#### Design #4 in "Armed" mode





#### Design #5 in "Armed" mode





#### **Decision Matrix**

		Designs											
		1		2		3		4		5		6	
Specifications	Weight	Score	Weight	Score	Weight	Score	Weight	Score	Weight	Score	Weight	Score	Weight
Compactness	0.2	3	0.6	2	0.4	3	0.6	2	0.4	4	0.8	5	1
Weight	0.2	3	0.6	2	0.4	4	0.8	2	0.4	5	1	5	1
Strength	0.3	3	0.9	5	1.5	4	1.2	5	1.5	4	1.2	4	1.2
Durability	0.2	3	0,6	5	1	2	0.4	3	0.6	4	0.8	3	0.6
Operational Speed	0.1	4	0.4	5	0.5	2	0.4	3	0.3	5	0.5	4	0.4
Total		3	3.1	3	3.8	-	3.4		3.2		4.3	4.2	

Designs 2, 5, 6 will be used for the interim design process



- Designed to keep payload stable during air operations
- Must be able to withstand aircraft maneuvers up to 2GS lateral load and 1G landing shock
- Sway brace may be able to adjust depending on the size/shape of payload
- Brace must be easy to use allowing the ground crew easily add and remove payloads.





### **Decision Matrix**

		Sway Brace Concepts							
			1	2					
Specifications Weight		Score	Weight	Score	Weight				
Weight	0.3	2	0.6	4	1.2				
Load carrying	0.3	5	1.5	3	0.9				
Store Size Flexibility	0.15	1	0.15	5	0.75				
Durability	0.1	4	0.4	2	0.2				
Ease of Use	0.1	5	0.5	4	0.4				
Simplicity	0.05	5	0.25	2	0.1				
Total		3.4 3.55			55				

# **Ejector Mechanism**

- Launcher will eject payload when "RELEASE" command is received from the aircraft.
- Free fall will not allow enough separation between the wing and payload
- Ejection velocity shall be a minimum of 10ft/s
- Net ejection energy of no more than 75 ft-lbs









### **Decision Matrix**

		Ejector Designs								
		1		2		3		4		
Specifications	Weight	Score	Weight	Score	Weight	Score	Weight	Score	Weight	
Weight	0.25	2	0.5	3.5	0.875	5	1.25	2.5	0.625	
Size	0.15	3	0.45	4	0.6	5	0.75	2	0.3	
Cost	0.1	2	0.2	3	0.3	4	0.4	2	0.2	
Safety	0.2	4.5	0.9	4	0.8	1	0.2	2	0.4	
Ease of Use	0.2	3	0.6	3	0.6	4	0.8	3	0.6	
Simplicity	0.1	3	0.3	3	0.3	2	0.2	4	0.4	
Total		2.95		3.475		3	.6	2.525		

# **Conclusion/Next Steps**

- Integration of our components into one cohesive system
- Develop a mechatronic system integrated with an intervalometer to organize sequence of events for payload release
- Engineering analysis on each component taking into account given constraints
- Interim Design

# **Questions** ????

### References

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