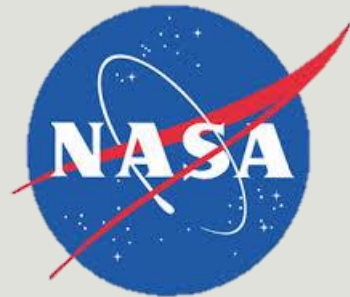


#20 - Direct Drive Solar Powered Arcjet Thruster

SPONSOR – NASA, MARSHALL SPACE FLIGHT CENTER, HUNTSVILLE AL

ADVISORS – DR. GUO, DR. KWAN, DR. ANDREI

SENIOR DESIGN COORDINATORS – DR. AMIN, DR. FRANK



Team Members

Date – 4/17/14

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Abstract

- **Project Scope:**
 - Design, fabricate, and test an electric arcjet thruster within a vacuum chamber that will be designed to simulate the space environment.
 - Operate via “direct-drive” in order to power the system.
- **Accomplishments:**
 - Thruster fabricated
 - Circuit designed and tested
 - Testing apparatus designed
 - Vacuum chamber tested
- **Future Recommendations:**
 - Adequate vacuum chamber needed
 - Acquire measurement devices to quantify performance
 - Incorporate solar panels

Sponsor Requirements

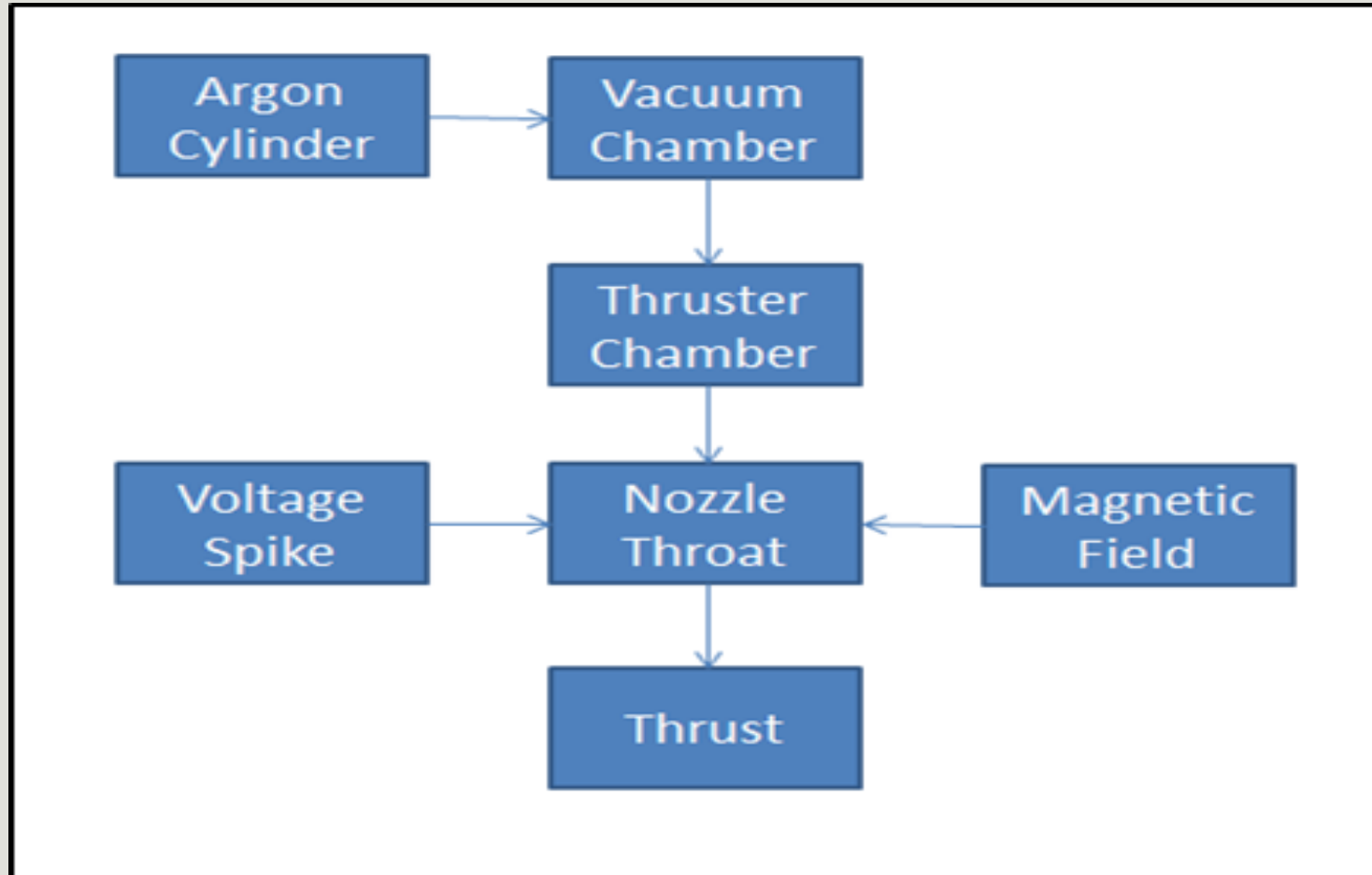
- **Eliminate the PPU**

- Generate a high-voltage pulse from a simple robust circuit
- Obtain power directly from solar panels or power supply

- **Design, manufacture, and test an arcjet thruster**

- Design and build a thruster capable of processing 50-400 W of power
 - Test under vacuum conditions
- Independently control propellant flow
- Design and execute a test plan to quantify the range of operating conditions where breakdown can be achieved
- Perform testing to see if a continuous discharge at these power/current levels can be sustained
 - Quantify the conditions over which this is possible

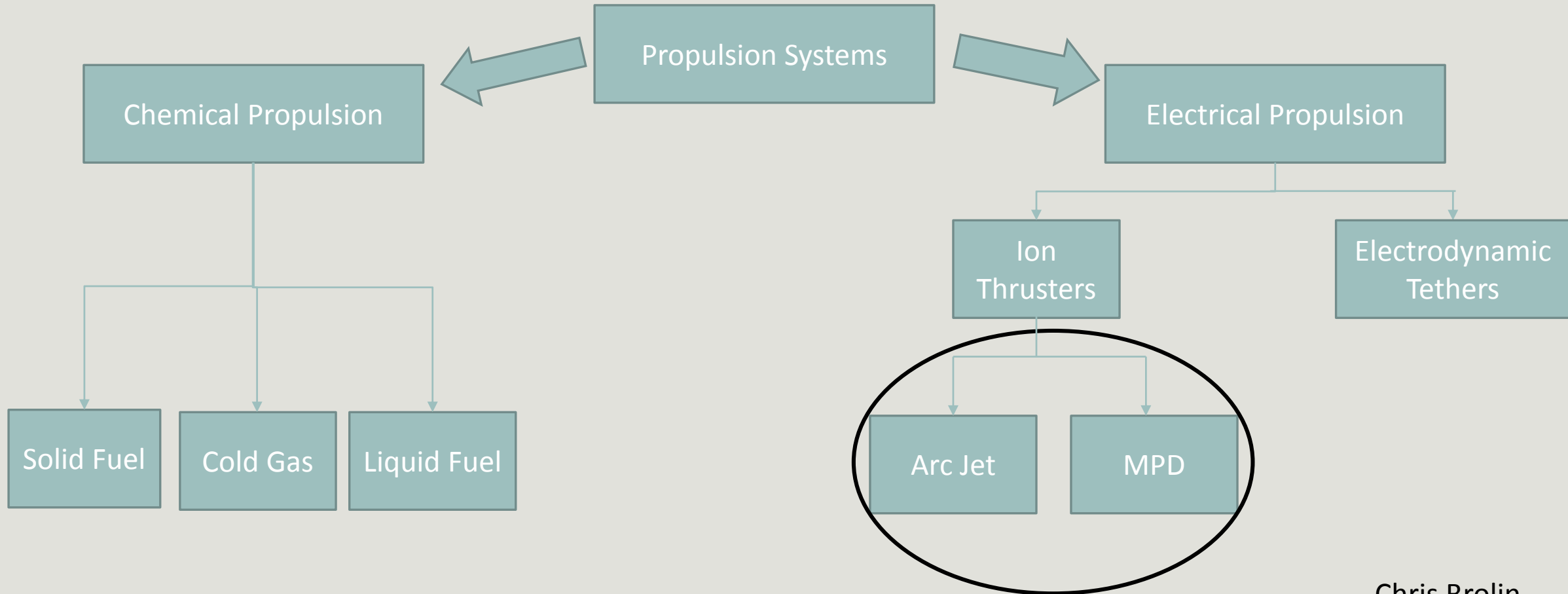
Functional Analysis



Background

- Electrical Propulsion Systems
 - High specific impulse – low thrust
 - Electro-thermal thruster– arcjet
 - Produce thrust by heating gas propellant (Ar) and expelling through C-D Nozzle
 - Electromagnetic thruster – MPD
 - Accelerates particles with applied magnetic force
- Purpose of Electric Propulsion Systems
 - Station keeping – lower overall lifetime costs
 - Satellite altitude and attitude adjustment
 - Potential for deep space applications
- Power Processing Unit (PPU)
 - Expensive and complex
 - Largest prohibitive component to electronic propulsion systems
 - Converts input power to correct current and voltage

Background



Paschen's Law

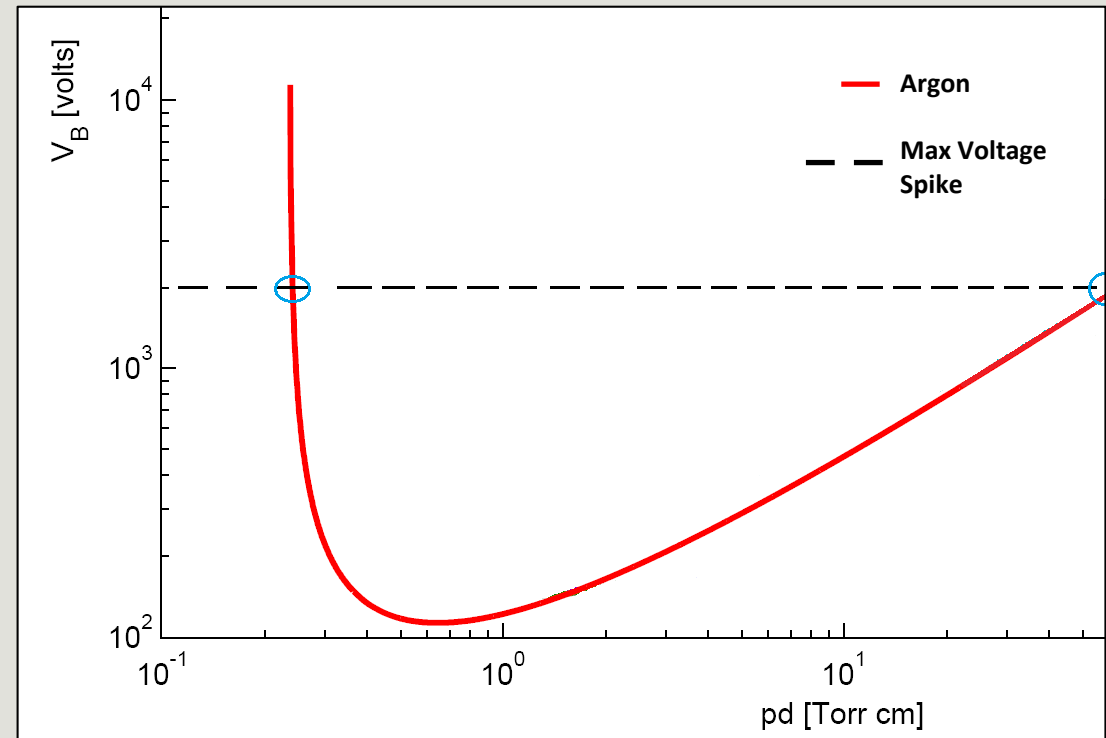
- Relates the product of pressure and distance between anode and cathode to the voltage necessary to initiate breakdown

$$V_{Breakdown} = f(P * d)$$

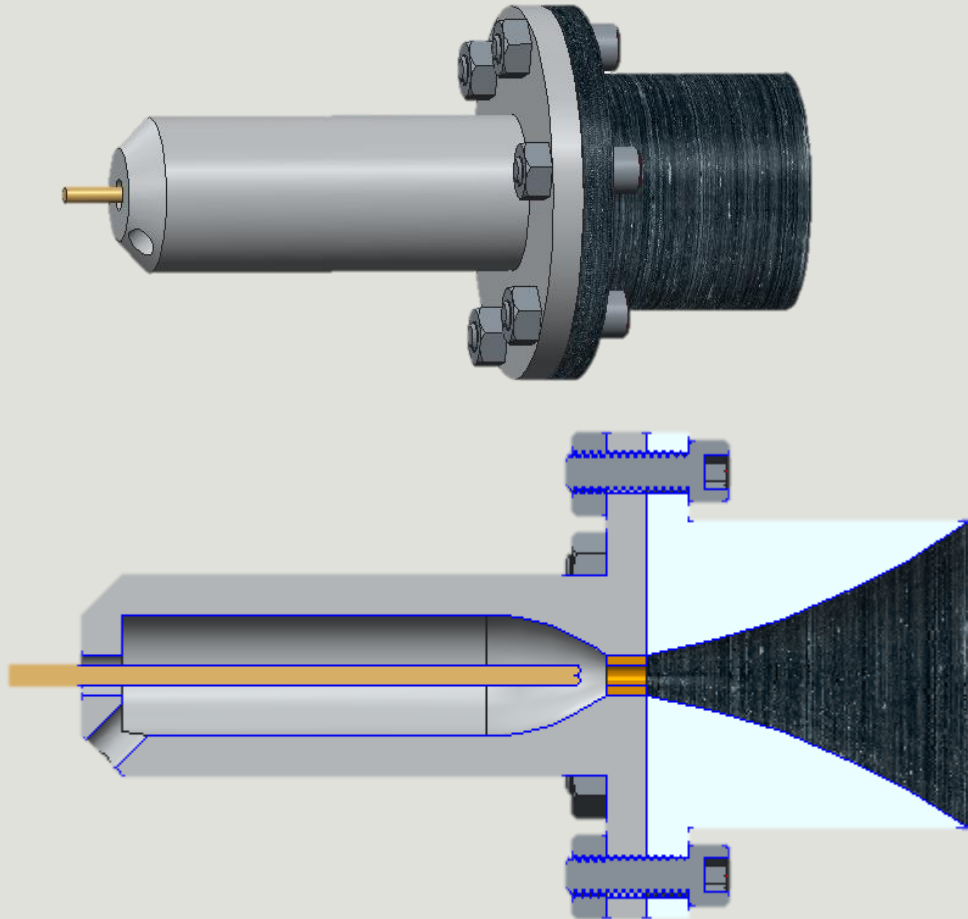
- Argon had lowest breakdown voltage

$$\sim 137 V$$

- Good starting point, but values will be different due to complex geometry



Initial Thruster Design



Characteristics

- Gas injected at angle
- Magnets more evenly spaced over nozzle

Pros

- Swirling gas helps to keep nozzle walls cool
- Metal nozzle is not part of circuit
- Magnets on diverging nozzle protect nozzle walls
- Conventional nozzle construction

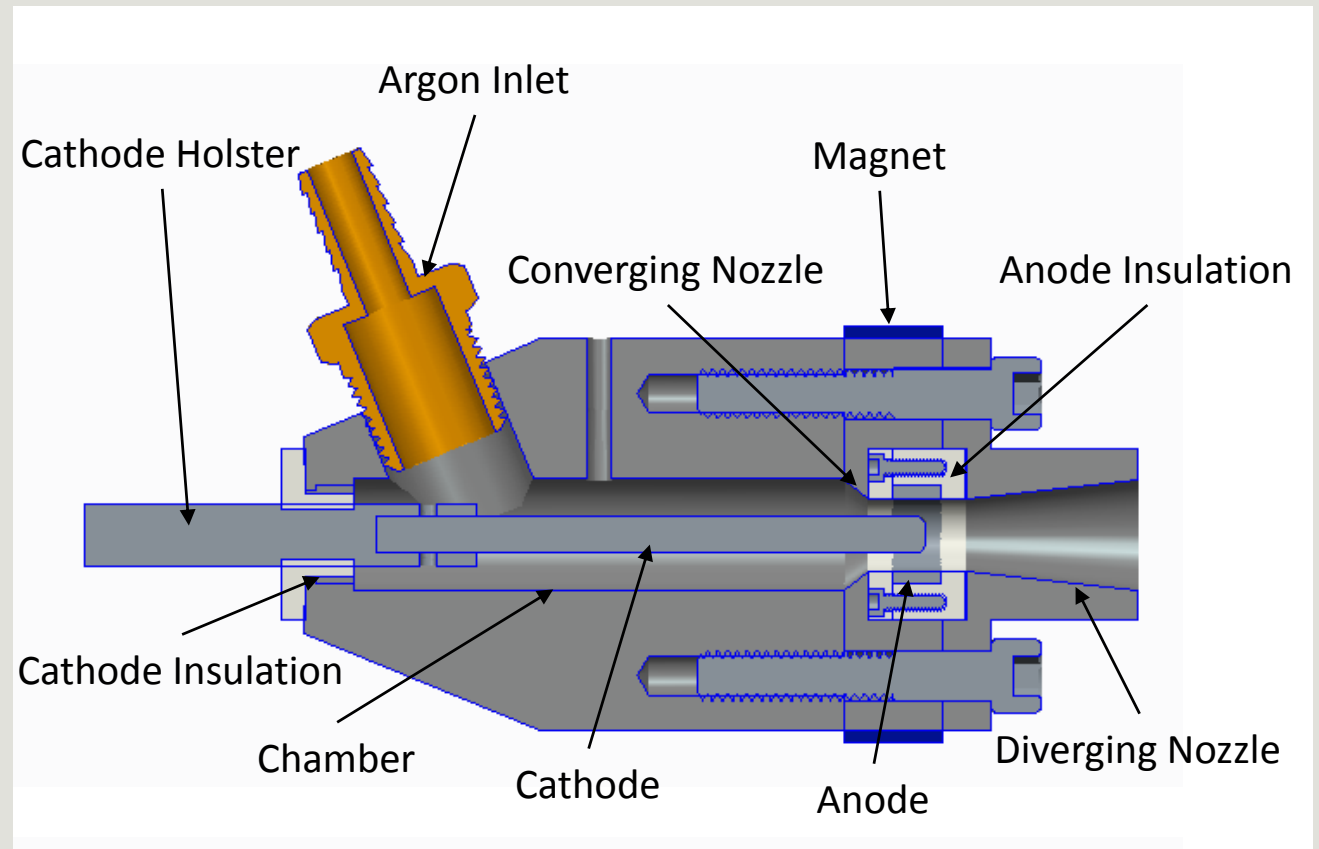
Cons

- More difficult to place magnet at diverging nozzle with flange location
- Difficult to complete circuit due to anode placement

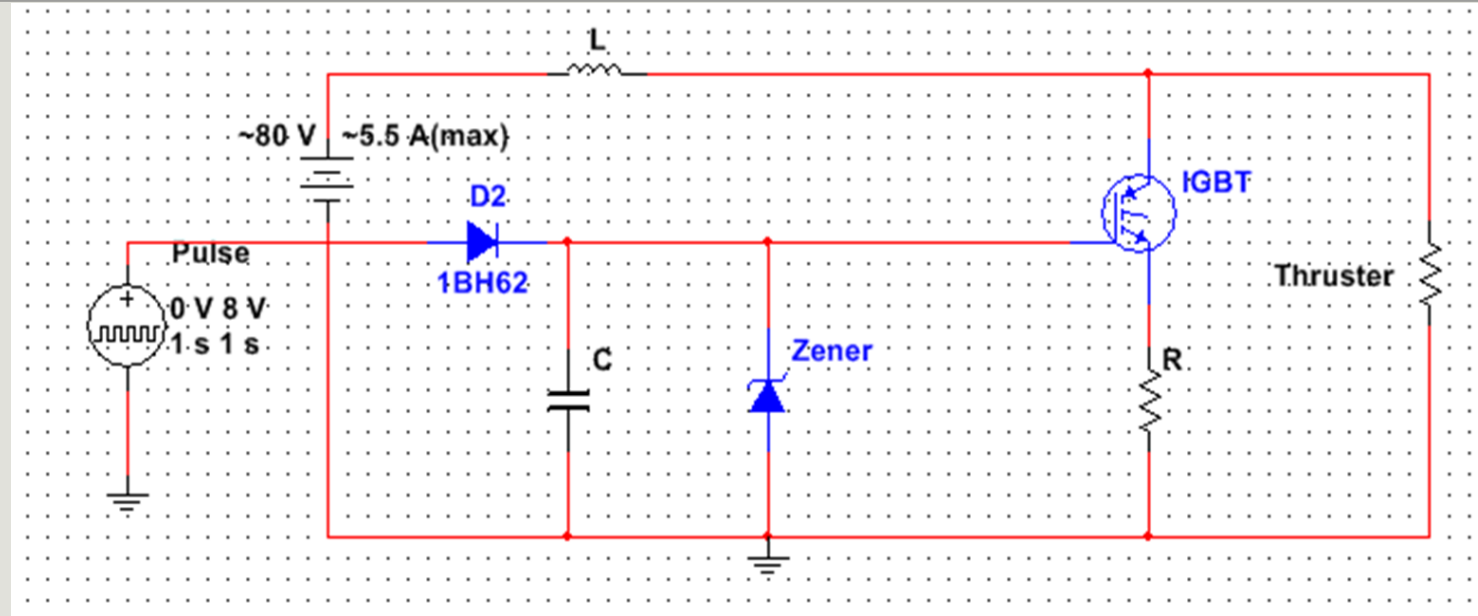
Final Thruster Design

Characteristics

- 3 part nozzle construction
 - Easier machinability
 - Designed for Mach 2.65 - $A/A^* = 3.15$
- Magnet placed at diverging nozzle to protect nozzle walls
- Stagnation Pressure – 550 Pa
- Static Pressure at throat – 267 Pa
 - Pressures from Bernoulli's Eq with const. mass flow rate
 - $P/P_0 = 0.4867$, at throat $M = 1$
- Anode/Cathode Spacing – 0.15"
- Product of pressure and distance gives breakdown voltage of 137 V
 - Well within circuit's capabilities



Initial Circuit Design

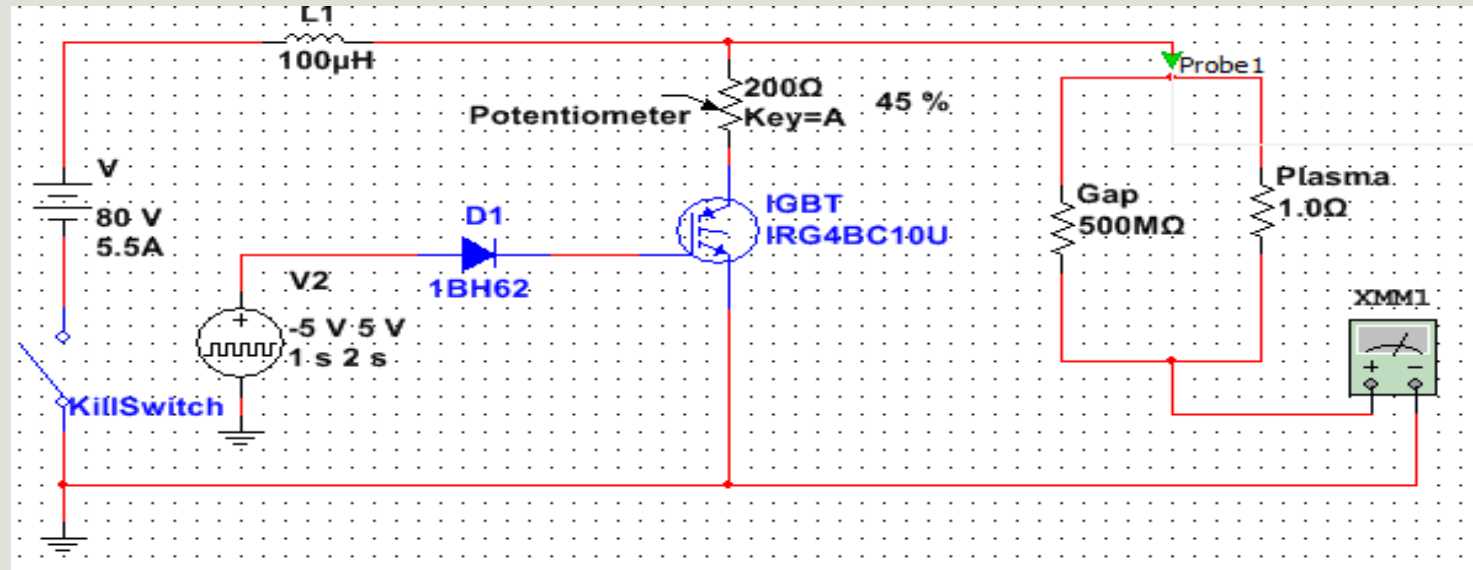


- Once in steady state: $I = \frac{V_S}{R}$ When the switch opens:

$$V_L = L \frac{di}{dt} = L \frac{I - 0}{dt} = L \frac{V_S}{R \cdot dt} \quad dt = 130 \text{ ns}, L = 100 \text{ uH}$$

- Theoretically capable of achieving 4.2 kV spike

Final Circuit Design



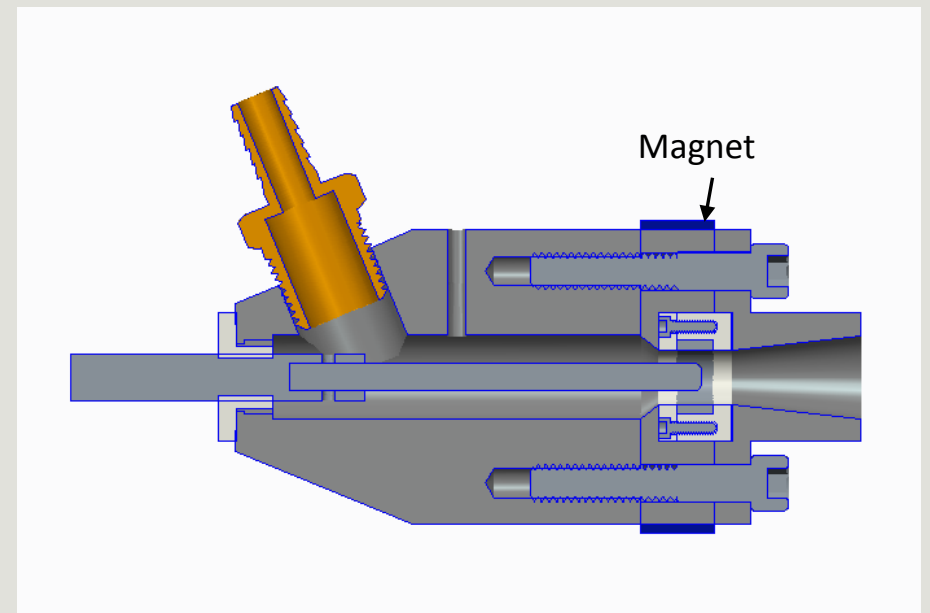
- The concepts of the circuit are the same but slightly modified
- No need for capacitor and Zener diode in parallel

Maximum Magnetic Field

- The desired magnetic field is given by $B = \frac{mv}{qr}$, $v = \sqrt{\frac{20eV}{3m}}$, where m is mass, v is velocity, q is charge, r is radius, eV is an electron-voltage, and B is the magnetic field. These equations simplify to give us:

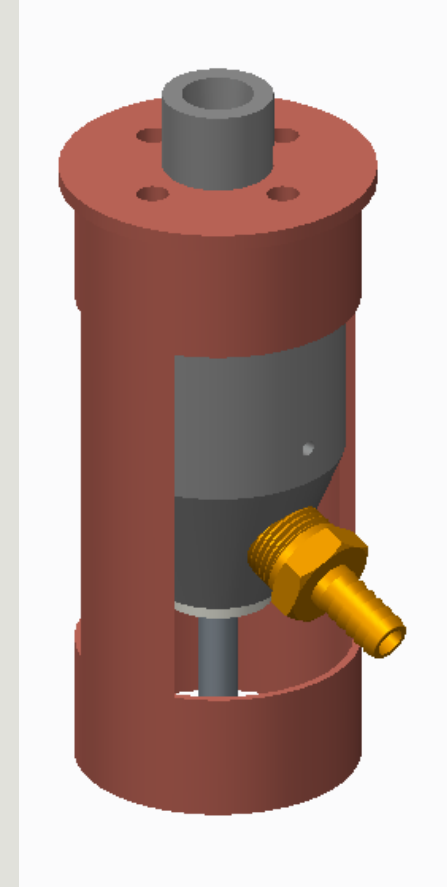
$$B = 0.316 \text{ T (calculated)}$$

- However, our sponsor advised us that any magnetic field would help
 - A flexible permanent magnet is used and rated at: **$B = 0.1 \text{ T at the center}$**



Test Stand

- Standard Pipe with cap
 - Separate Pieces
- Easy to machine
- Easily attached to thruster and detached for any required adjustments
- Lightweight
- Easy to access argon and pressure ports
- Adaptable for whatever force measurement equipment is used



Vacuum Chamber Components

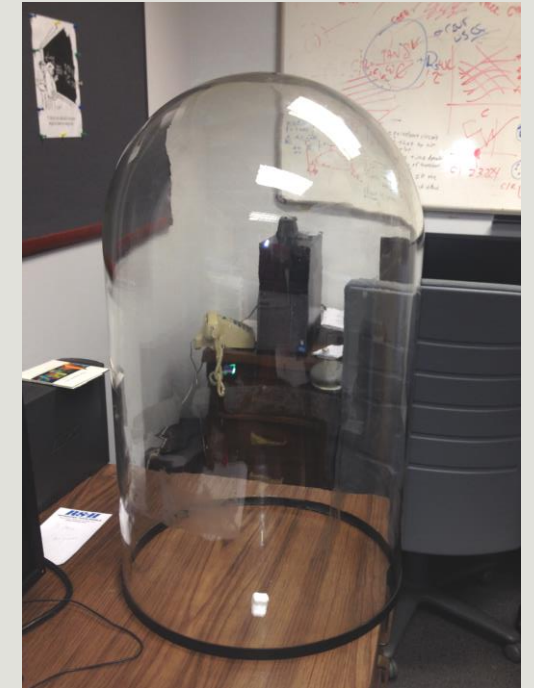
Vacuum Pump

- Welch 1400
- Vacuum rated to 1×10^{-4} Torr



Vacuum Chamber

- Owen's Corning Bell-Jar
- 18" x 30" x 0.5"
- Donated by Dr. Weatherspoon



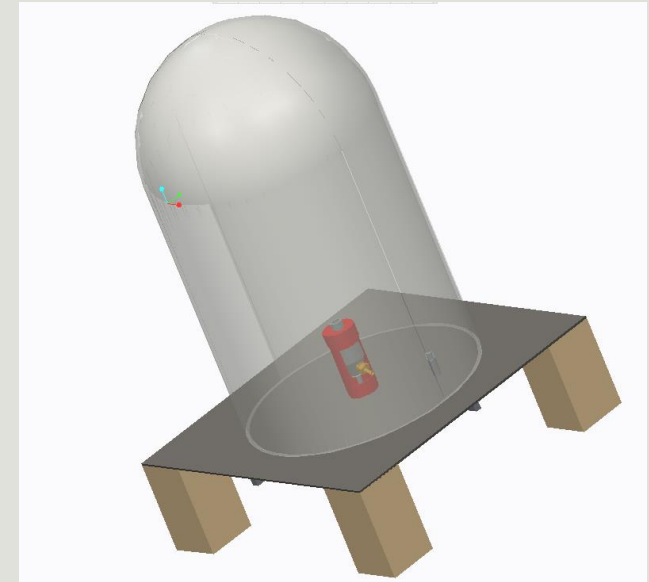
Baseplate

- Donated by Dr. Weatherspoon
- Argon and electrical connection input through baseplate
- Reinforced to withstand absolute vacuum

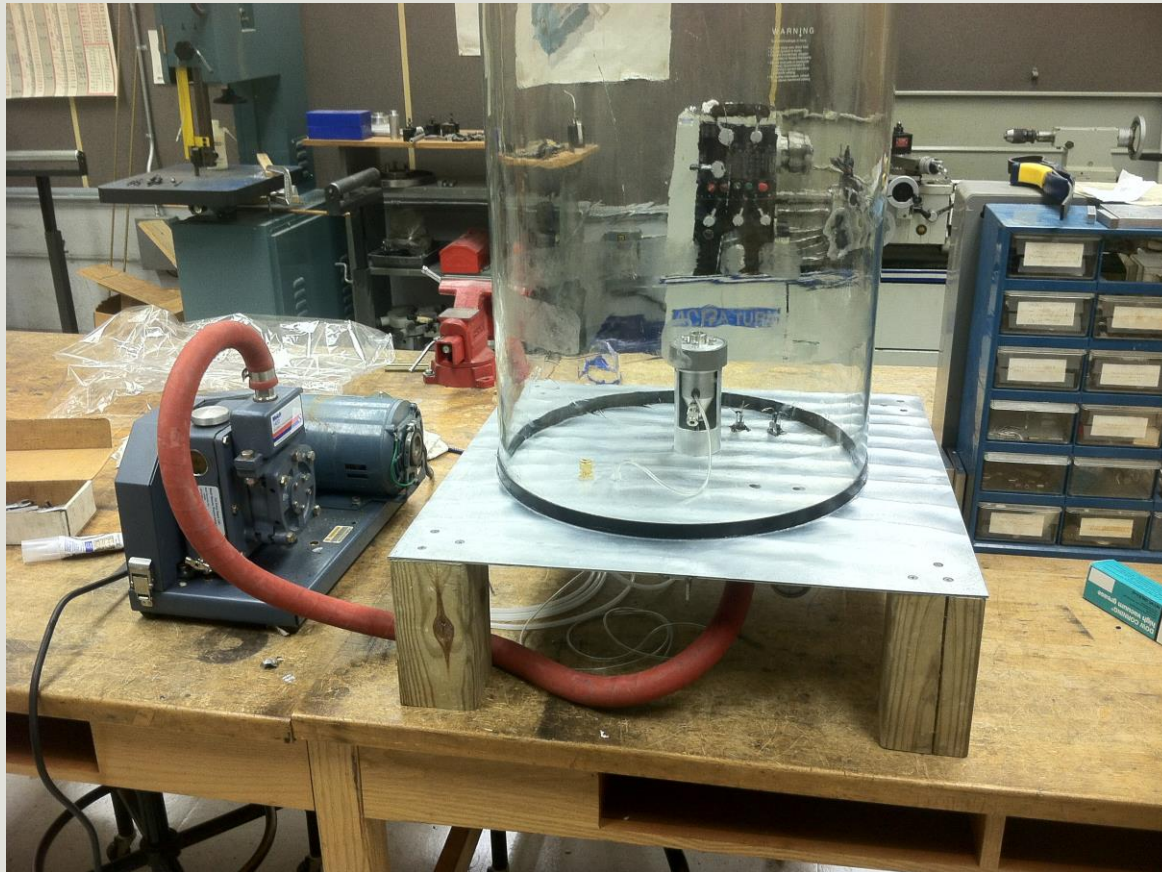


Final Testing Set Up

- Angled steel reinforced baseplate
- Pipes welded for
 - Vacuum hose
 - Vacuum gauge
 - Argon inlet
- Wires throughput with stycast epoxy
 - Supplied by Dr. Guo
- Edges of chamber sealed with vacuum grease



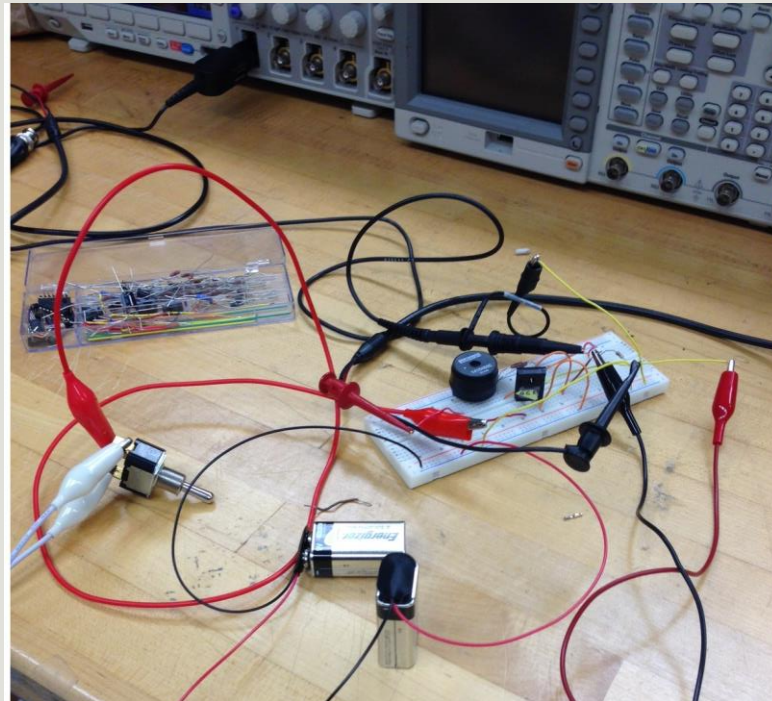
Vacuum Testing



Cory Gainus

Circuit Test and Results

- Full Circuit Testing
- Approximately 150 V spike at $V_{source} = 20$ V and $R_{top} = 50$ ohm
- Theoretical max spike 2 kV



Final Testing

- Vacuum pump supplied by Dr. Guo from Magnet Lab
- Attempted the ionization of Helium
 - Argon not readily available in Magnet Lab
- More accurate vacuum gauge
 - Vacuum of 300 miliTorr (approx. 40 Pa) was achieved
- No pressure transducer available
 - Difficult to know what pressure of Helium was inside thruster
- Limited power supply options
 - Limited voltage spike capabilities
- Voltage spike of approx. 400V was achieved
 - Unfortunately no ionization event occurred



Summary

- **Electrical Design:**

- Circuit:

- Circuit designed, implemented and tested
 - Maximum voltage spike of 2 kV

- Magnet:

- Magnetic field was calculated and implemented with flexible permanent magnet around test stand
 - Still needs testing to verify effectiveness

- **Mechanical Design:**

- Thruster:

- Thruster designed, fabricated
 - Unable to test due to lack of proper measurement equipment

- Vacuum Chamber:

- Baseplate outfitted and reinforced to be able to withstand the vacuum
 - Tested using Welch 1400 vacuum pump
 - Vacuum gauge was cheap and inaccurate
 - Vacuum pump and gauge provided by Dr. Guo achieved vacuum of 0.3 Torr (approx. 40 Pa)

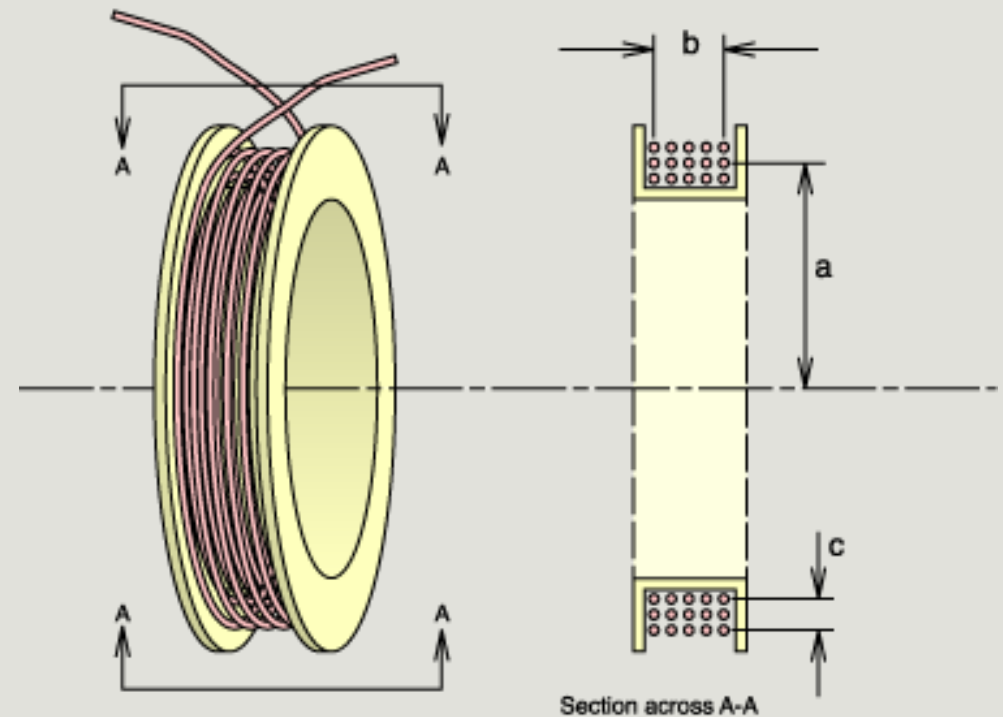
- Breakdown:

- No ionization event was achieved

Future Recommendations - Magnet

- Max Current = 5 A
- Length = 0.01905 m
- Diameter of 22 gauge wire = 0.0017 m
- Number of loops per layer = 11
- Absolute max field = 0.316 T = 4790 A-turns
- Typical ideal field = 0.050 T = 758 A-turns
- At least 14 layers needed
 - Coat with layer of insulation between wire layers

Fig. 1 Dimensions of a multi-layer coil of rectangular cross section



Future Recommendations – Vacuum/Test

- **Adequate Vacuum Chamber Needed**
 - Current vacuum chamber and pump were donated
 - A more precise vacuum gauge is required to accurately measure vacuum.
- **Make Use of High-Voltage Plasma Laboratory**
 - Argon supply
 - High-voltage power supplies readily available
 - Higher rated electrical probes
 - Experience dealing with plasma generation

Future Recommendations - Measurement

- **Acquire measurement devices for testing**
 - Measuring thrust
 - Load Cell
 - Measuring Housing Temperature
 - Thermocouple
 - Measuring Voltage Spikes
 - Differential voltage probes
 - Chamber Pressure Measurement
 - Differential Pressure Transducer

Questions?

Thank You for Your Time!