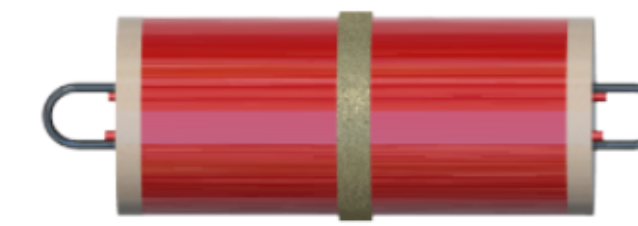
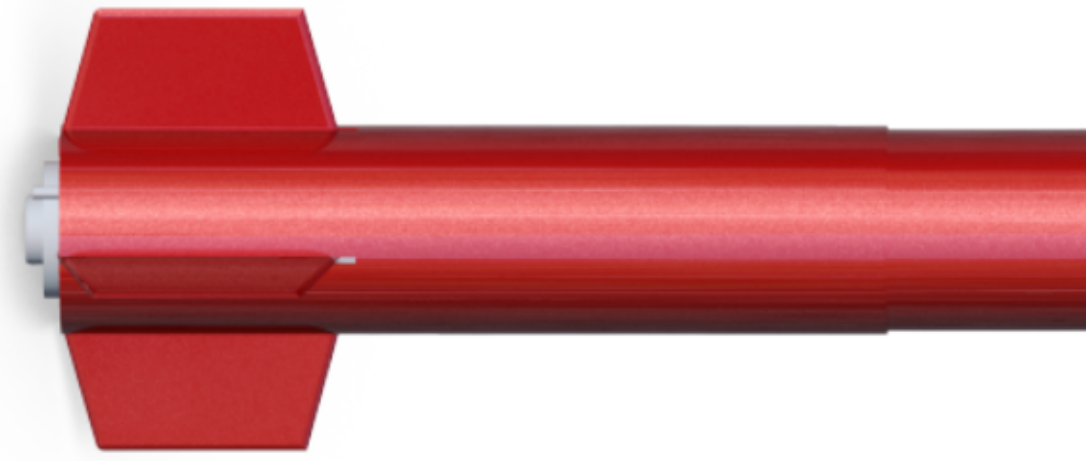


# Team 24: Designing and Flying an Experimental Sounding Rocket

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## Acknowledgements

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## Project Scope

Design and construct a rocket capable of carrying an experimental payload to be launched and safely recovered within the parameters of the 2017 Intercollegiate Rocket Engineering Competition hosted by the Experimental Sounding Rocket Association.

## Design Requirements

### Payload

- 8.8 lb minimum
- 10cm x 10cm x 11.35cm (CubeSat)
- Scientific experiment or technology demo

### Recovery

- Dual Deployment required for vehicles 1,500+ ft
- Drogue: 70-150 ft/s
- Main: < 30ft/s

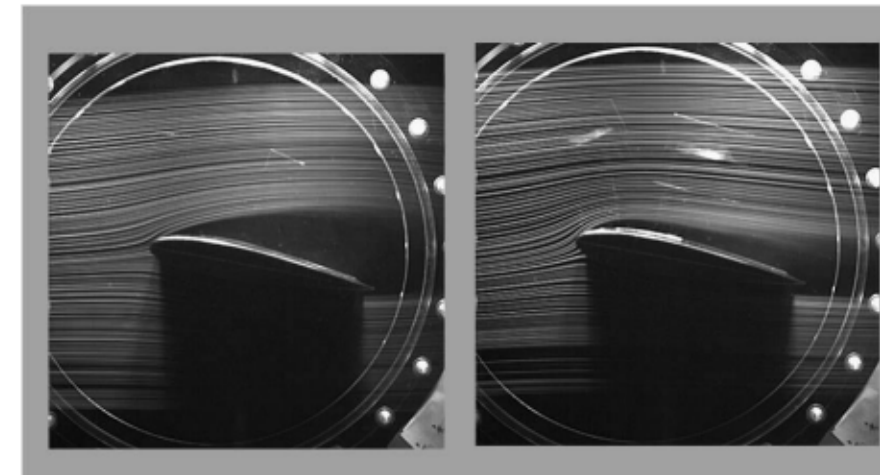
### Electronics

- 1 COTS altimeter
- Redundant electronics
- GPS module

## Flow Control Payload

### Theory

- Measure the effect of injecting fluid into the surrounding air.
- Injecting fluid can be used to reduce or create drag on a surface



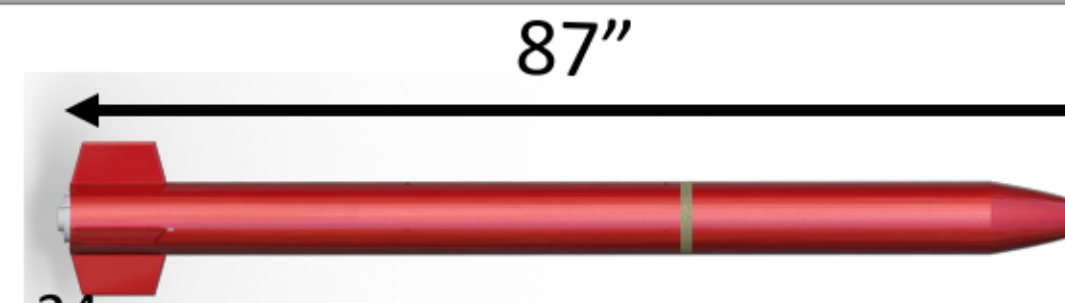
### Application

- Most parachute failures occur due to improper alignment
- Alignment of rocket can be controlled through active flow control
- Through using micro-jets in the nose cone of the rocket, a more reliable parachute deployment event can hypothetically be created.

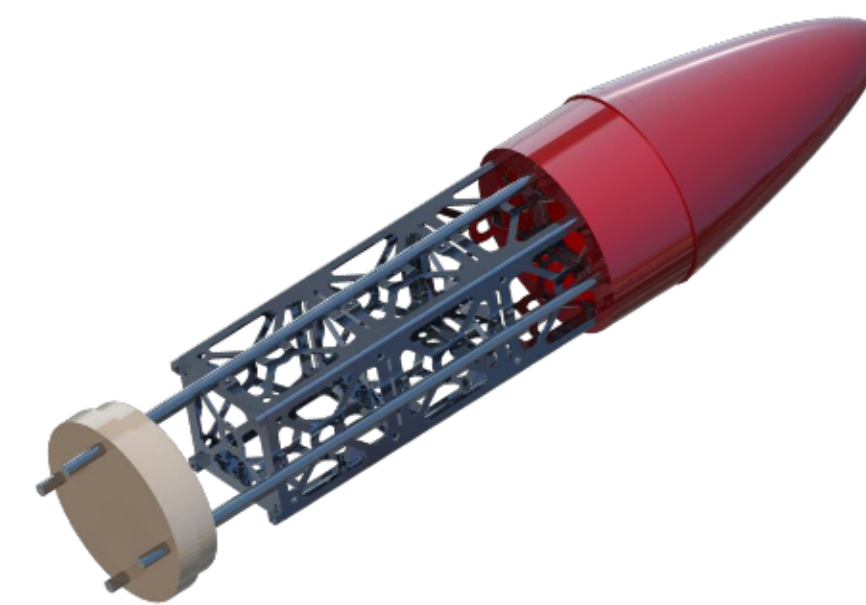
## Rocket Design

### Overview

- 54 lb
- 6 inch diameter
- Fiberglass body
- 4 main compartments
- Fully recoverable
- Manufactured by Team 24



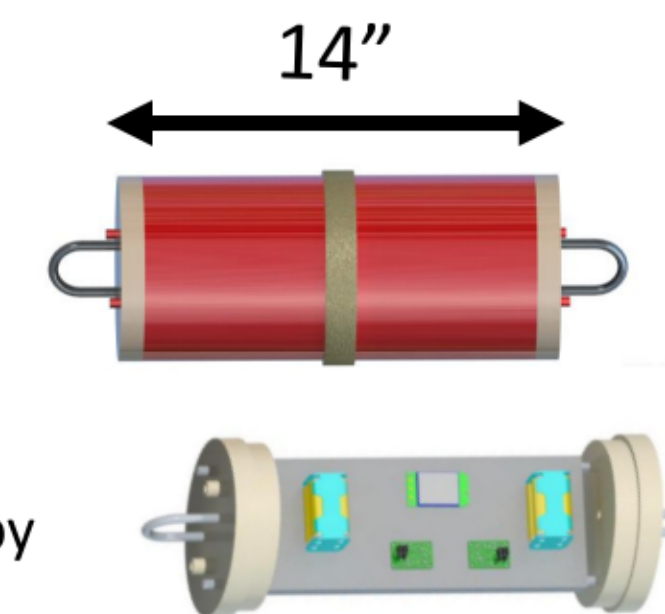
### Nose Cone and Payload Housing



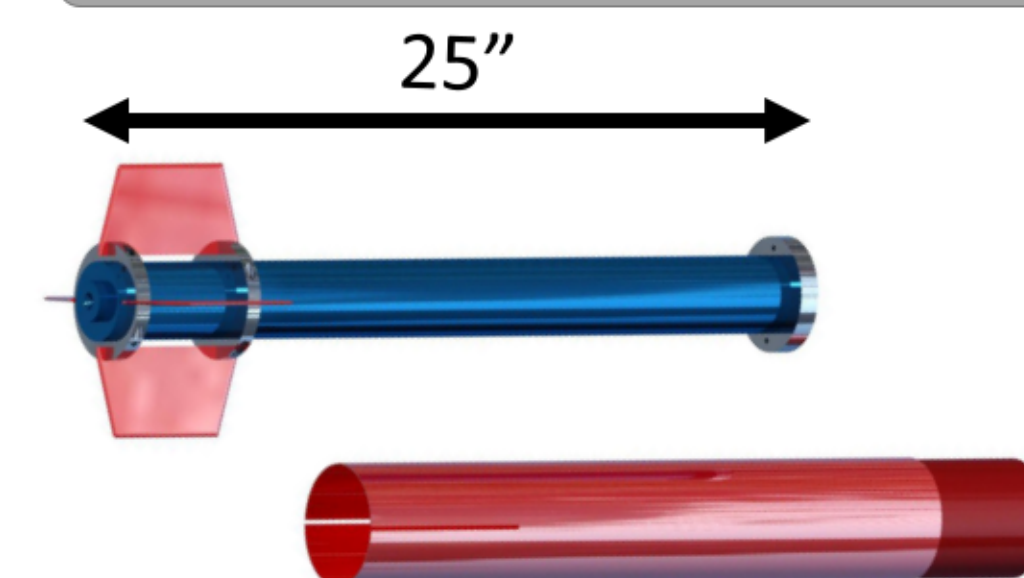
- 3U CubeSat removable payload housing
- Aluminum payload frame
- Parabolic nose cone shape for minimal drag
- 3D printed nose cone with incorporated coupler section
- 3D printed mounting rings for anchoring CubeSat unit
- Easily accessible for quick payload removal and replacement

### Avionics Coupler

- StratoLoggerCF avionics system
- S.R.A.D backup avionics
- Redundant power supplies
- Duplicate critical wiring harness
- 3D printed mounting platform
- Sealed endcaps for protection
- Exposed center lip for sensor packages
- Heavy duty U-Blots for parachute mounting
- GPS module a transceiver
- Nichrome igniters controlled by flight computer



### Booster Segment



- Fin-through-body design for secure fin and motor mounting
- Removable fin setup for fin shape experimentation
- High strength aluminum motor housing
- Removable design for interchangeable motors

## Simulation Results

### OpenRocket <sup>[6]</sup>

Data	Value
Apogee	10,082 ft
Max. Velocity	794 ft/s
Max. Acceleration	214 ft/s <sup>2</sup>
Center of Gravity	57.5 in
Center of Pressure	65 in

### In-House Simulation

Data	Value
Apogee	10,025 ft
Max. Velocity	799 ft/s
Max. Acceleration	215 ft/s <sup>2</sup>

### Motor Selection

Using both an in-house and an industry standard simulation software, Team 24 was able to select the ideal motor for theoretical weight and flight characteristics.

**Aerotech M1845**      Burn Time: 4.4s  
Total Impulse: 1867 lb/s      Max Thrust: 543.68 lbd



## Summary

Team 24 has designed, and intends to fly, a large 54lb rocket for the purpose of competing in the ERSR IREC competition in late June. Based on the data shown, we are confident that our design can execute a successful flight and land safely. It is our hope that our rocket is competitive and is capable of scoring well.

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