

ROBOTIC TRASH CART

FAMU-FSU Engineering

Team 311: Jacob Emerson, Oscar Flores, Bishoy Morkos, John Williams

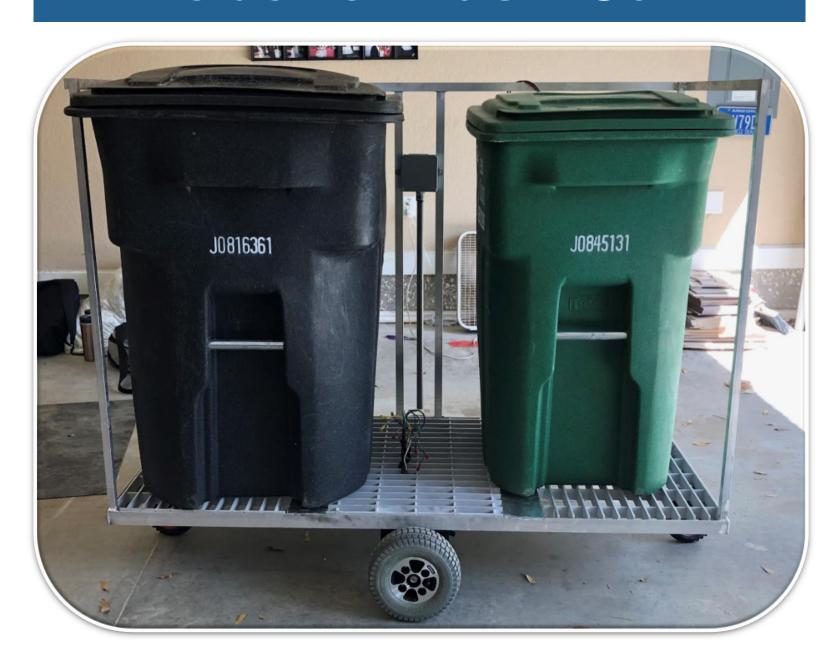
Project Background

The Robotic Trash Cart (RTC) will transport both waste containers from the home base to the curb for waste pick up using a controller. The RTC design is focused on senior citizens, the disabled community, and people with limited mobility and strength in their extremities.

Assumptions

- Largest gradient that will be traversed is
 5 degrees of incline (ADA)
- Florida weather: rain, wind, humidity
- Pathway is paved
- RTC will be stored outside of the house
- Waste engineers will return the bins to the RTC after dispensing the waste

Robotic Trash Cart

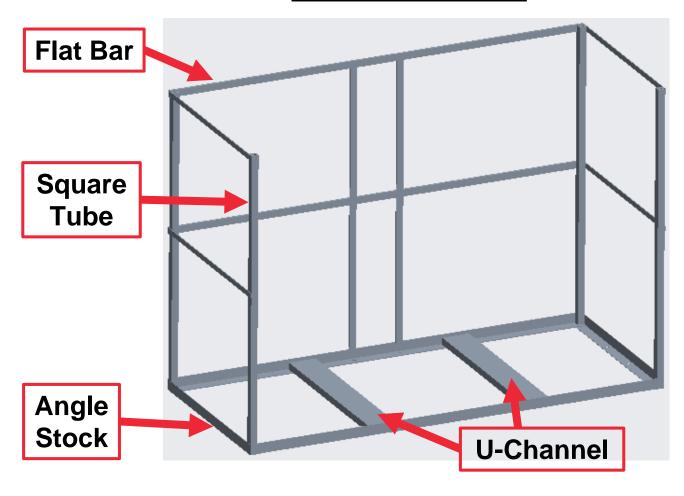


- Rectangular, aluminum frame
- Mid–Wheel drive
- Wireless controller
- Zero point turning
- Gates allow easy access to containers

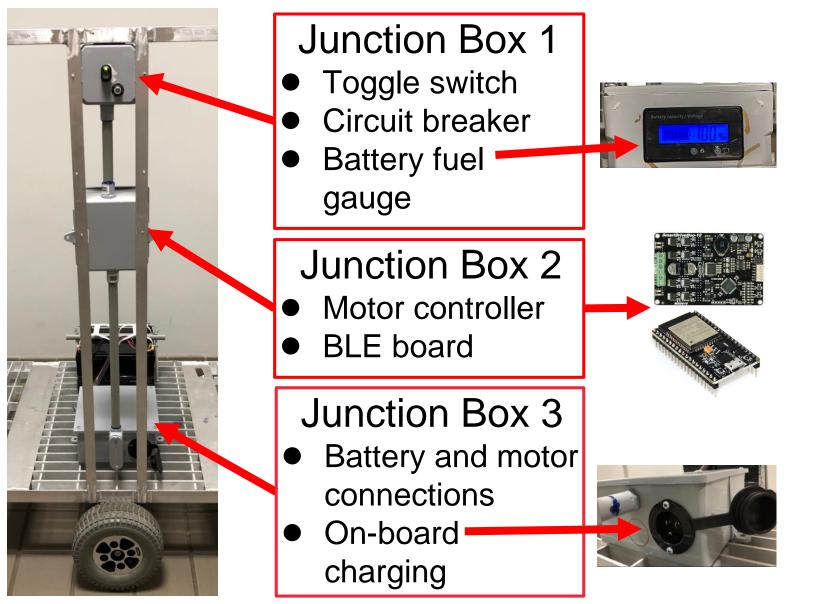
Design

Front View Junction Boxes Batteries Gate

Model Frame



Circuit Wiring



Frame

Aluminum Frame

- Anti-corrosive
- High strength-toweight ratio

Base Material

- Fiberglass square grating
- Lightweight
- Durable
- Prevents any issues with pooling water

Control System

The motors will be controlled using pulse width modulation and a free mobile application (RemoteXY).

SmartDriveDuc-10

Cytron Smart Drive Duo

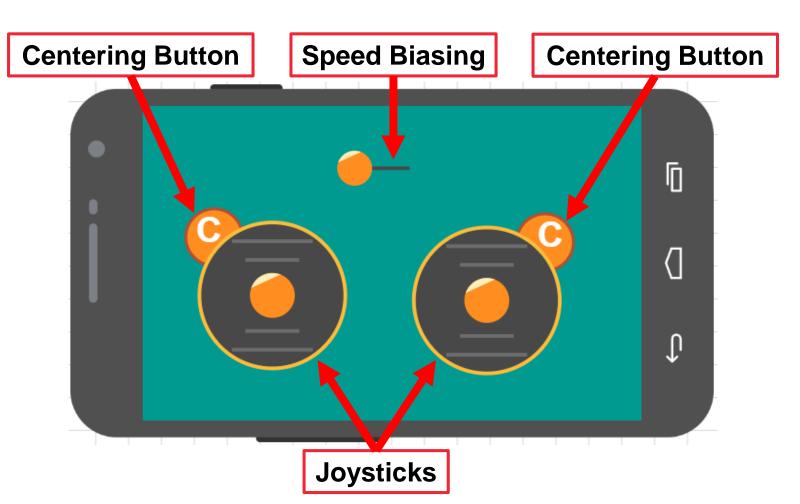
PWM capabilities

- Brushed motor controller
- Dual channel

ESP32 Wi-Fi/BT SOC

- Wi–Fi and BLE capabilities
- Arduino compatible

RemoteXY Mobile App



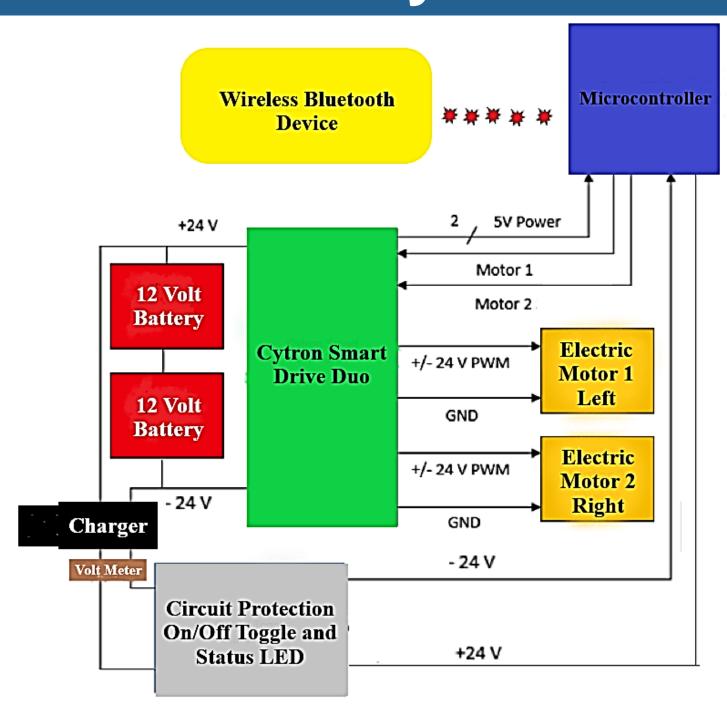
Drive System

CIM 24V DC Motors

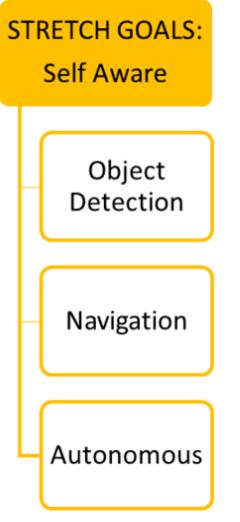
- Brushed Motors
- Torque: 115.3 N-m
- Capable of moving a 200 lb load up a 5 degree incline



Power System



Future Applications



We are working on implementing autonomous functionalities.

- Scheduling capabilities
- Synchronization with garage doors
- Future Applications
 - Single unit autonomous trash bins