



Virtual Reality Tracking and Haptic Feedback Gloves

Team Introductions



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Project Background

- Sponsor: Lockheed Martin
- The purpose of this project is to improve current virtual training systems at Lockheed Martin through the design of Virtual Reality gloves that will reduce the cost and size of current simulation systems while still providing feedback to the user



Figure 1: A Lockheed Martin F-35 Flight Simulator



Figure 2: A Lockheed Martin M1A2 Tank Simulator

Alexandra Hollabaugh

Important Terms and Acronyms

- Haptic feedback: Feedback provided by the gloves in response to interaction with the virtual environment
- Tactile feedback: Feedback provided by interaction with the real world environment
- IMU: Inertial measurement unit
- LRA: Linear resonant actuators

Customer Needs



- Provide haptic feedback when interacting with the virtual environment
- Provide tactile feedback when interacting with the real world
- Durable design while maintaining a low profile
- Able to easily transfer from one user to the next
- Allows for uninhibited range of motion
- Hypoallergenic and easily sanitized

Alexandra Hollabaugh

What is VR?

- VR stands for virtual reality and is a relatively new technology
- A headset allows for full emersion into a virtual world
- Wands are used as controllers to interact with the environment while providing limited feedback



Figure 3: Example of an HTC VIVE Pro Headset and Controller

Drawbacks of Existing VR Gloves

- Current examples are expensive
- Have numerous wires and tubes connected to the base
- Do not retain the ability to feel interactions with a non-virtual environment
- Use bulky tracking systems

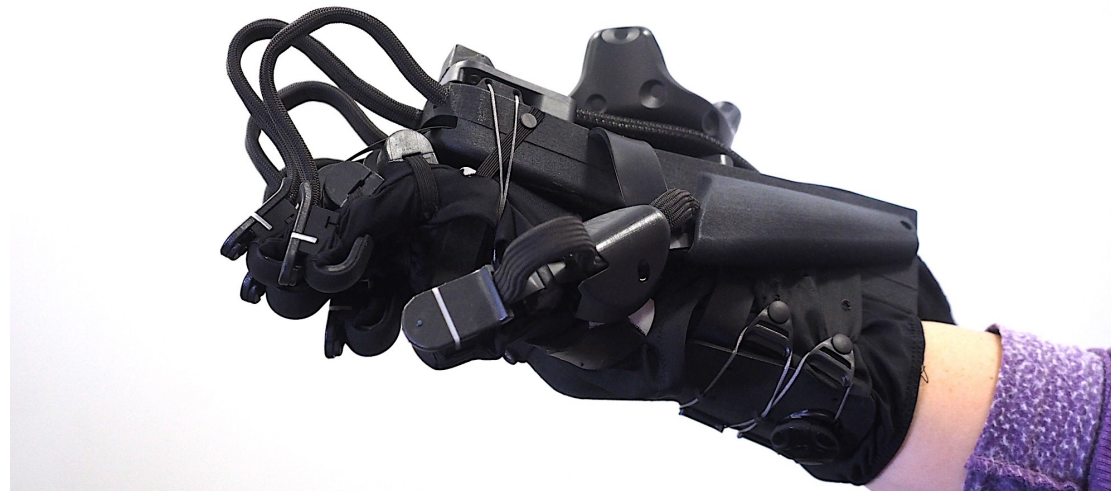


Figure 4: Example of current Haptic Feedback Glove. (HaptX glove)

Jake Kennedy

Project Goals



- Design a pair of gloves that are portable, lightweight, and durable
- Provide haptic feedback for the palms of both hands and all ten fingers
- Track both hands and all ten fingers in real time in the Unity environment
- Overall design compatible with the HTC Vive VR system

Jake Kennedy

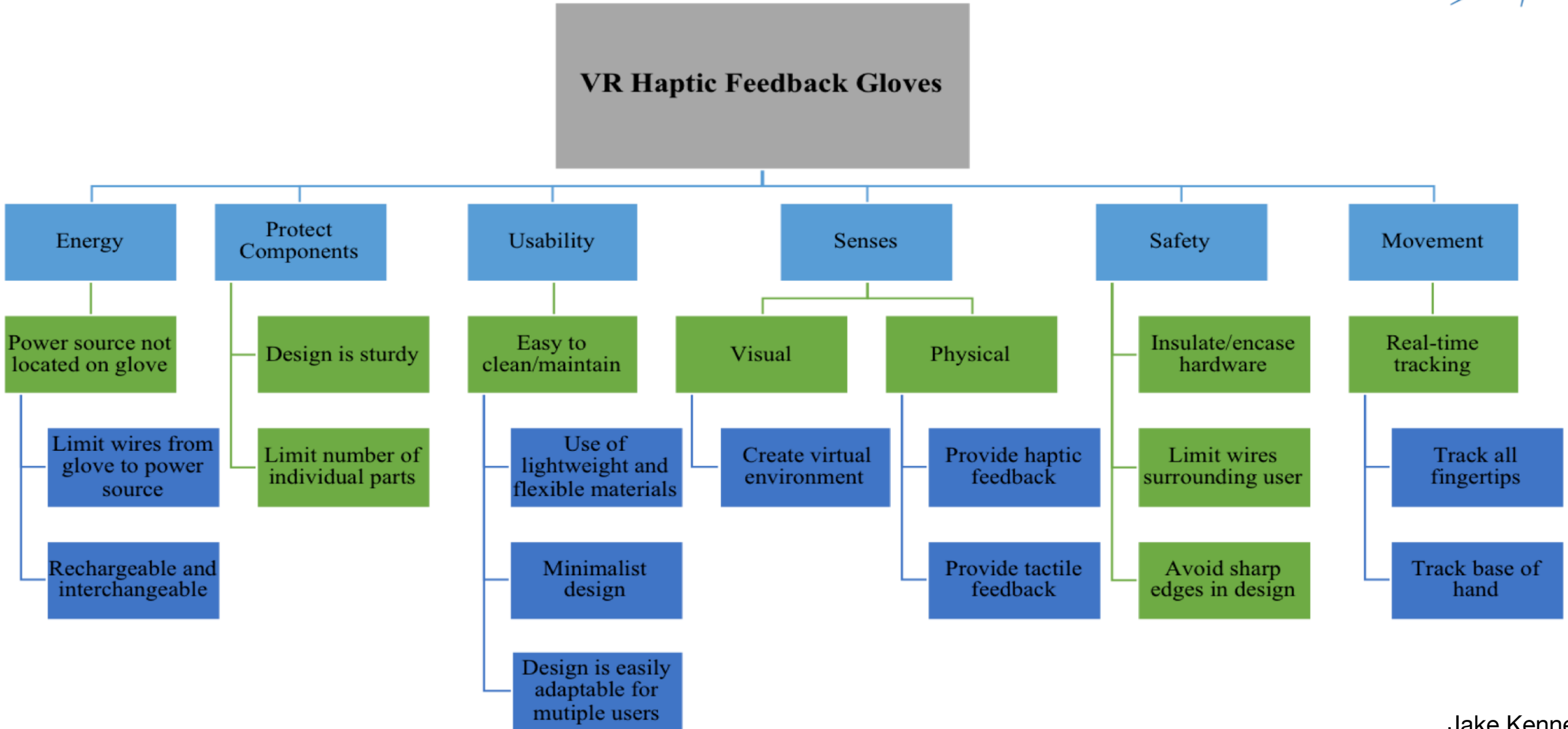
Targets

Table 1: Most Important Targets and Metrics

Metric	Target
System latency	20 milliseconds
Tactile feedback	Sensation of touch retained
Haptic feedback	Physical response to interaction with virtual environment

- From the customer needs the following targets were determined
- These were then used to determine the engineering characteristics

Functional Decomposition



Jake Kennedy

Functional Decomposition (cont'd)



- Track the movement of hands and fingers in real time
- Provide haptic and tactile feedback for the hands
- Allow design to be easily adaptable for multiple users

Jake Kennedy

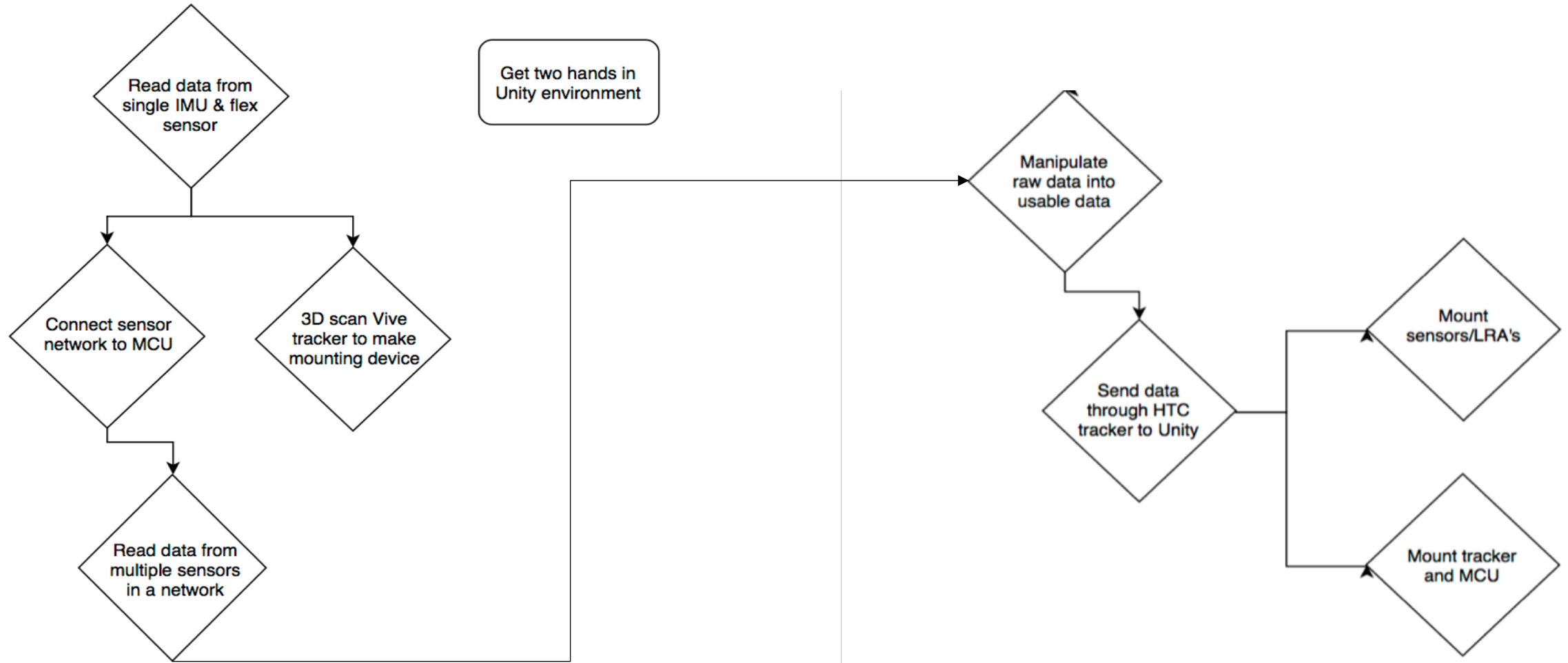
Design Concept

- Fingerless gloves
- 12 LRAs, 1 on each palm and front of each finger
- Removable rechargeable battery on back of each hand
- Raspberry Pi Zero on the back of each hand
- 12 9-axis IMUs, 1 on the back of each finger and hand



Figure 5: Final concept components

Moving Forward



Jonathan Roberts

Challenges Moving Forward

- Mount electronic hardware
- Connect sensor network to microcontroller
- Integrate hardware with virtual environment
- Making wiring low profile (i.e. conductive thread, etc.)

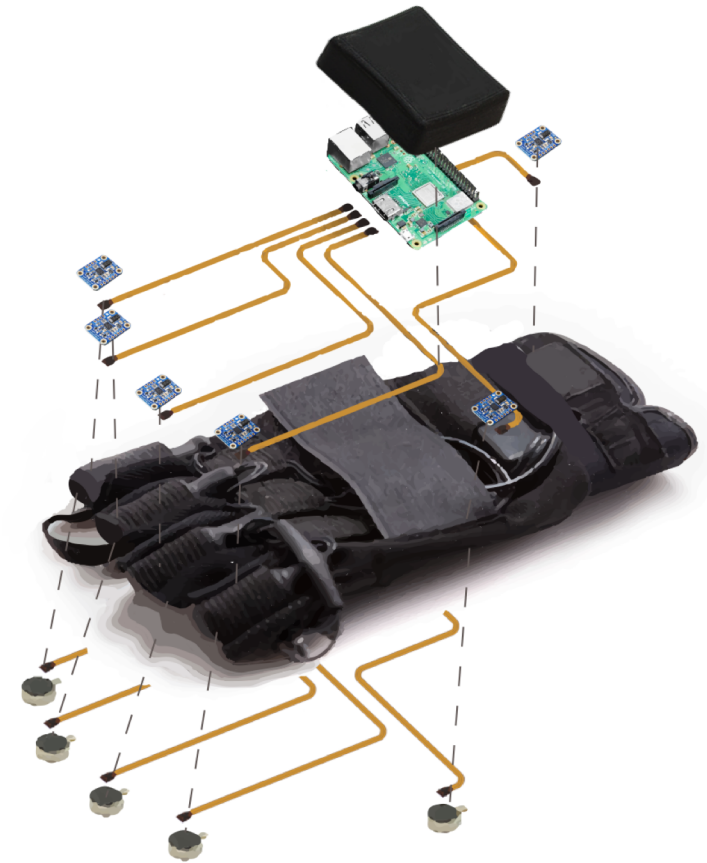


Figure 6: Layout of components for glove design

Prototyping and Testing



Figure 7: IMU's with Raspberry Pi Zero



Figure 8: LRA's with Raspberry Pi Zero



Figure 9: Flex Sensors, IMU's, Raspberry Pi Zero

Jonathan Roberts

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