

### **Concept Generation**

Concept generation is a process in which the team collaborated to idealize possible solutions for our design problem. The team was tasked with generating 100 ideas. This was done in order to stimulate new perspectives on how to best solve the engineering problem brought forth by Corning. A variety of methods were used to generate ideas.

#### **Concept Generation Tools**

The team utilized a few concept generation tools to branch new ideas while completing the 100 design concepts. Using biomimicry, the team analyzed the movements and activities of animals and discussed how these properties could be applied. For example, concept 22 is a bird wing inspired gate mechanism. Crapshoot was utilized to produce out of the box ideas based on the different functions we needed out of the design. The team also utilized a lot of brainstorming to inspire each other and branch off our individual thoughts.

### Medium Fidelity Concepts

Five medium fidelity concepts were selected out of the 100 design concepts. These medium fidelity concepts achieve most of the necessary goals, but due to conflicting opinions the team is unsure of their overall success.

Table 1	I: Medium Fidelity	

Concept #	Description
8	Self-nesting T's
42	Have Swedish wheels moving mechanically in opposite direction
45	Add 2 long poles on sides of V's



50	Pressure sensor gate between V's	
72	Add sandbag weights to pallet	

### **High Fidelity Concepts**

Three high fidelity concepts were selected out of the 100 design concepts. The team is highly confident these designs will satisfy the needs and have very high chances at being successful. The medium and high-fidelity concepts will be compared against each other throughout the concept selection process.

Table 2: High Fidelity

Concept #	Description	
5	Four bar mechanical system with an overhang where needed	
34	Weight-activated pincers	
65	Magnetic locking swivel	

# High Fidelity Concept #5

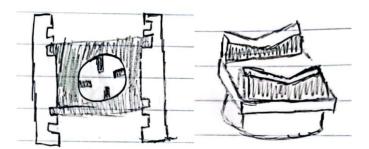




Figure 2: High Fidelity Concept #5

# High Fidelity Concept #34

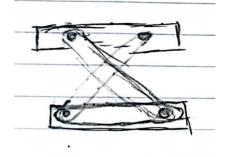


Figure 3: High Fidelity Concept #34

## High Fidelity Concept #65



Figure 2: High Fidelity Concept #65



### **Concept Generation (100 Concepts)**

- 1. Robot Arm to remove T's
- 2. Add springs in chucks
- 3. Tension-Based Mechanical System
- 4. Coded Lift Gate
- 5. Four bar mechanical system with an overhang where needed
- 6. Inflatable barriers on sides of faces
- 7. Rubber friction on V-chucks
- 8. Spring loaded T-self nesting
- 9. Change v-chuck angle
- 10. Make v-chuck circular
- 11. Electro mechanical Side clamps
- 12. Strap around the ceramic
- 13. T-hinged (Hinges on Ts)
- 14. Camshaft leverage mechanism
- 15. Actuator on chuck to Release T-pin and T's lay down
- 16. Drones flying over to pick up T's
- 17. Rail to ceiling to wrap around ceramic and follow conveyor
- 18. Bumps on conveyor to eject T's
- 19. Pinball punchout T's
- 20. Rod-slide mechanism
- 21. Drop down walls
- 22. Bird wing inspired open and close flaps



- 23. Slap-bracelet style brace
- 24. Foam dampener in v-chuck
- 25. Overhang to click the spring up/down like a pen
- 26. Vibration offset machine
- 27. Electro mechanical shock absorbers on chucks (self adjusting)
- 28. Extend v-chucks inward
- 29. Extend v-chuck using spring (fold out)
- 30. Net on outside of conveyor
- 31. Add a heavyweight onto pallet
- 32. Add PTFE layer on bottom of pallet
- 33. Bridge between V's made of foam
- 34. Weight-activated pincer
- 35. Rollers on face of V's
- 36. Swedish wheels on V
- 37. Lay ceramic flat on face and change the direction of the imaging system
- 38. Lay ceramic flat on face and add more mirrors in the imaging system
- 39. Add net to V to hold the ceramic
- 40. Lay ceramic flat on the face and add robot arm to move ceramic on chucks for imaging
- 41. Spray ceramic with sticky coating then wash and dry
- 42. Have Swedish wheels moving mechanically in opposite direction
- 43. Have Swedish wheels moving electro-mechanical in opposite direction
- 44. Add bumpy surface to V's to ad friction



- 45. Add 2 long poles on sides of V's
- 46. Make V's thicker to account for all length ceramics
- 47. Make V's thicker to account for all length ceramics and add material to close off hole
- 48. Sorbothane V's
- 49. Add safety net between V's
- 50. Pressure sensor gate between V's
- 51. Have the robot hit the switch for the closure of lift gate
- 52. Have the robot hit switch camshaft leverage
- 53. Roller to brace ceramics (dumbbell shape)
- 54. Strap with magnetic connectors
- 55. Magnetic V's and magnetic spray ceramics
- 56. Gyroscope V
- 57. Get rid of V's and make a hammock out of elastic material to hold ceramics
- 58. Make the V's hover by attaching to poles and elastic band
- 59. Add IMU inside V's
- 60. Change T material to make it allow for imaging
- 61. Hydraulic shocks
- 62. Mechanical swivel mechanism to chucks
- 63. Add velcro to ceramics and V's
- 64. Electro-Mechanical swivel
- 65. Magnetic locking swivel
- 66. Combined swivel and gyroscope



- 67. Add springs to mechanical swivel
- 68. Add springs to electro-mechanical swivel
- 69. Add spring to magnetic swivel
- 70. Rotating upper section of T
- 71. Mimic mountain goat hooves
- 72. Add sandbag weights to pallet
- 73. Put bubble wrap on the bottom
- 74. Add carpet to plant floor
- 75. Train switch swivel with built-in dampening
- 76. Magnetorheological fluid
- 77. Electrorheological fluid
- 78. Silly putty cushion with conforming bowl
- 79. Add silly putty and sandbags
- 80. V-shaped fins 90 degrees from v chuck
- 81. Foam pit around conveyor
- 82. Add a cutting station and keep the part long for conveyor transport
- 83. Make V's always in tension
- 84. Magnets on tops of T's, large overhead magnet
- 85. Drones carry ceramics
- 86. AC motor to fold/raise the T's
- 87. Cut hole in top of imaging system and add robot to grab T's
- 88. Magnetize entire conveyor so pallets float (bullet train)
- 89. Make conveyor actually stop so there is no vibrations



- 90. T's made from ice that dissolve at imaging system
- 91. Bubble wrap ceramics
- 92. rope around ceramic with snipper robot
- 93. Set ceramics on top of sand
- 94. Enclose pallets with clear material
- 95. Make pallet out of foam
- 96. Romba(<sup>TM</sup>) that drives T carts back to start
- 97. Smaller T's that can be scanned through
- 98. Add a C slot and extra V's
- 99. Add sand around conveyor
- 100. Put wall on conveyor