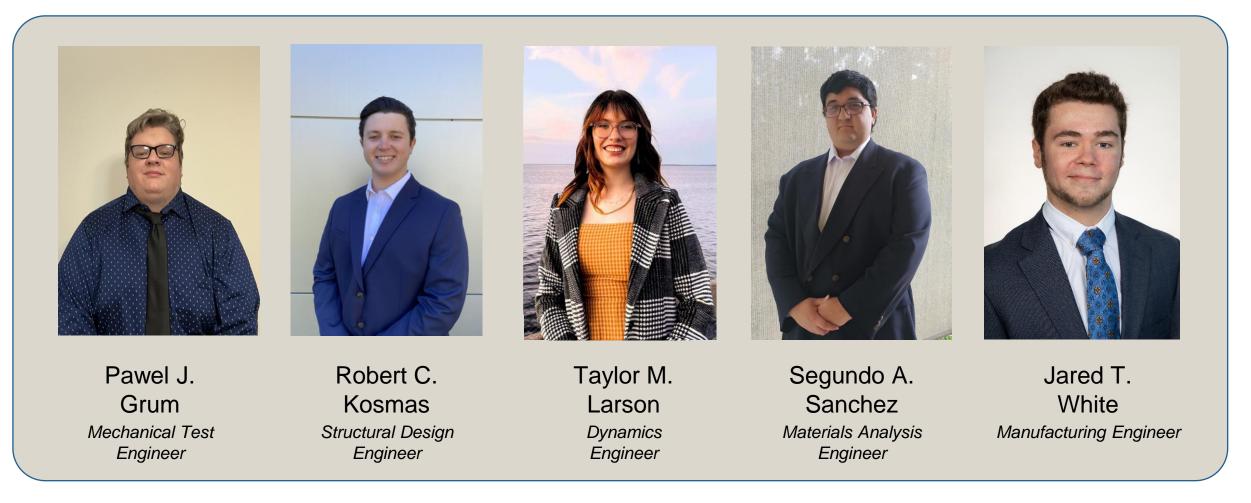
# Team 506: Corning Plugger Pallet Short Part Stabilization

Pawel J. Grum | Robert C. Kosmas | Taylor M. Larson | Segundo A. Sanchez | Jared T. White

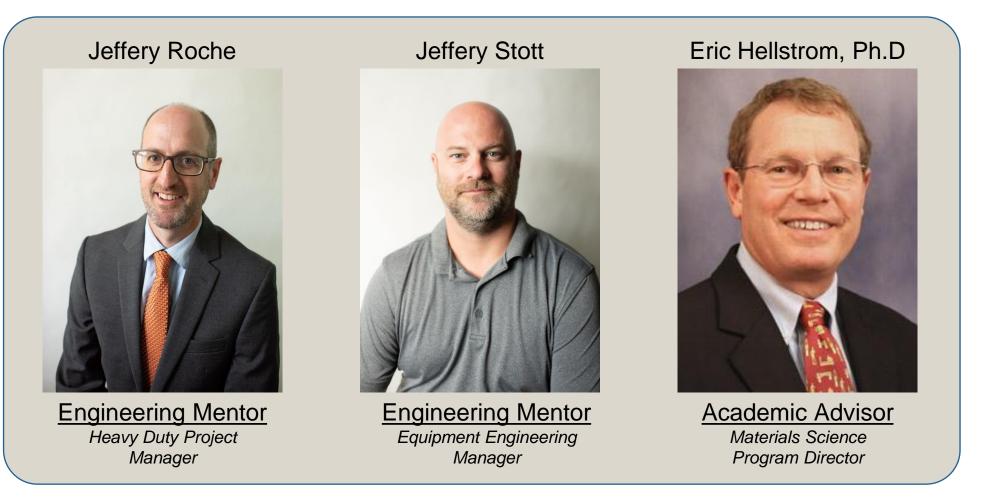
### **Team Members**



Segundo Sanchez



## **Sponsors and Advisors**



Segundo Sanchez



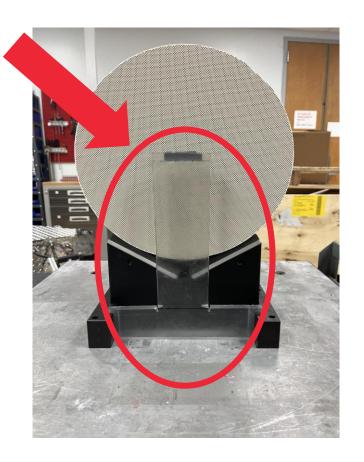
## **Project Objective**

The objective of this project is to produce a stabilization system to protect ceramics on Corning's conveyor while reducing the required manual labor.



## **Project Background**







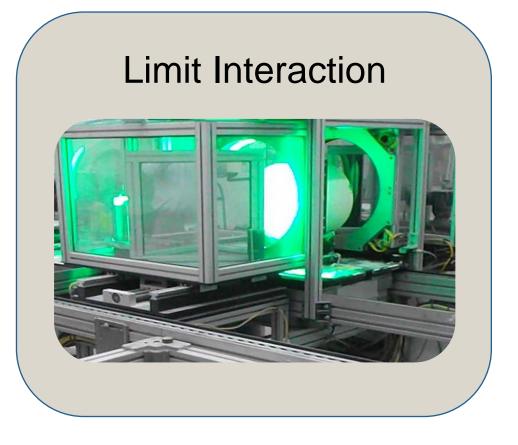
Segundo Sanchez







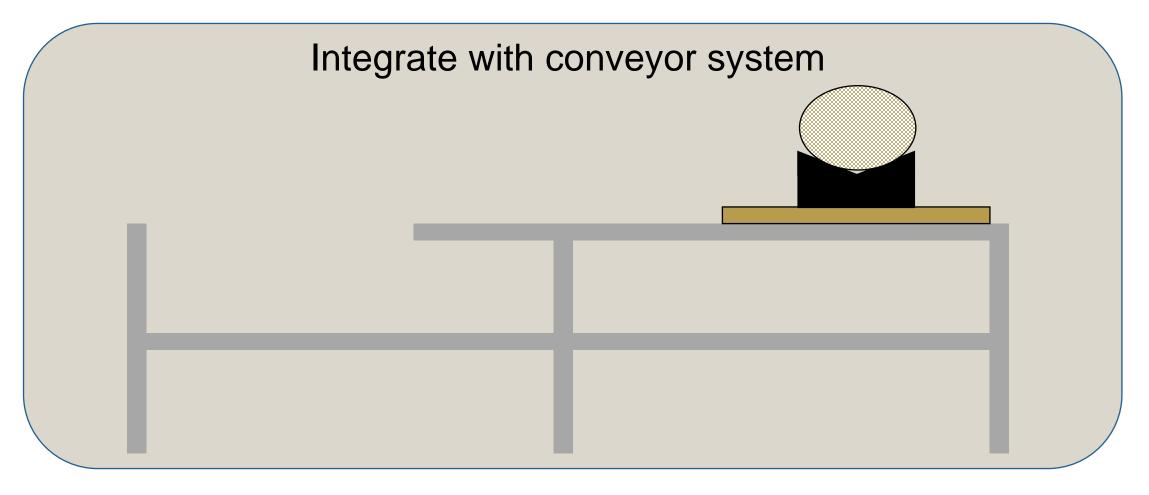




Segundo Sanchez







Segundo Sanchez

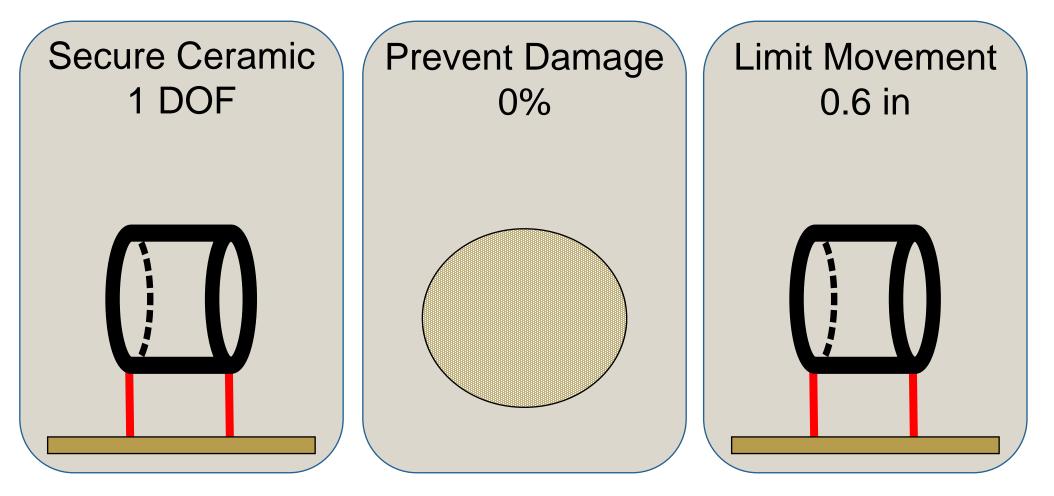


### **Targets and Metrics**



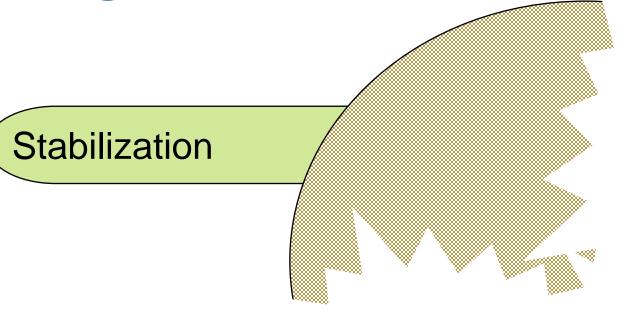


## **Stabilization Metrics**



Segundo Sanchez

### **Targets and Metrics**

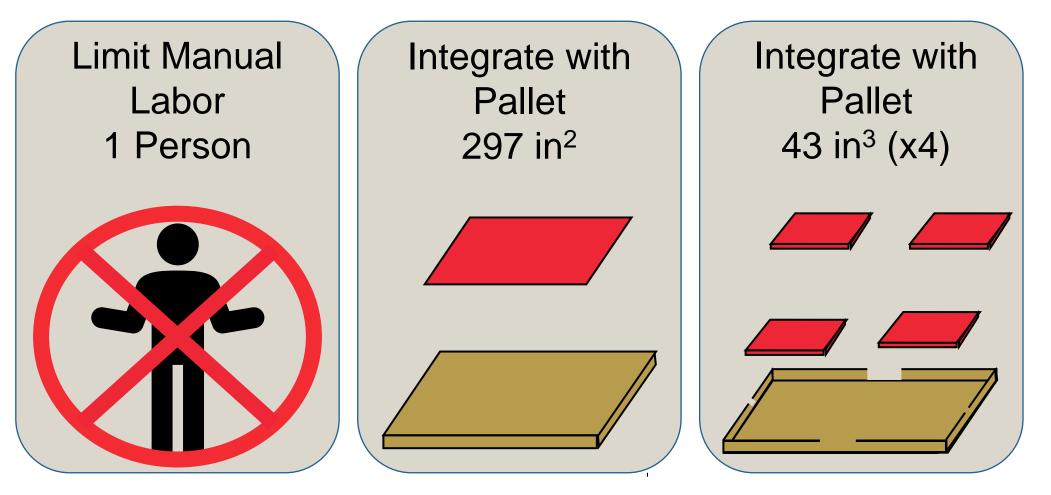




Segundo Sanchez



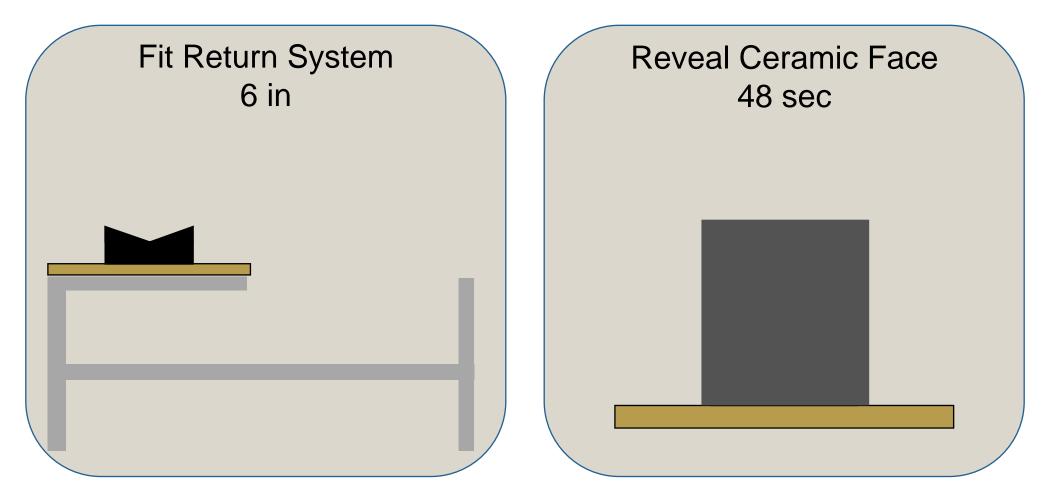
# **Compatibility Metrics**



Segundo Sanchez

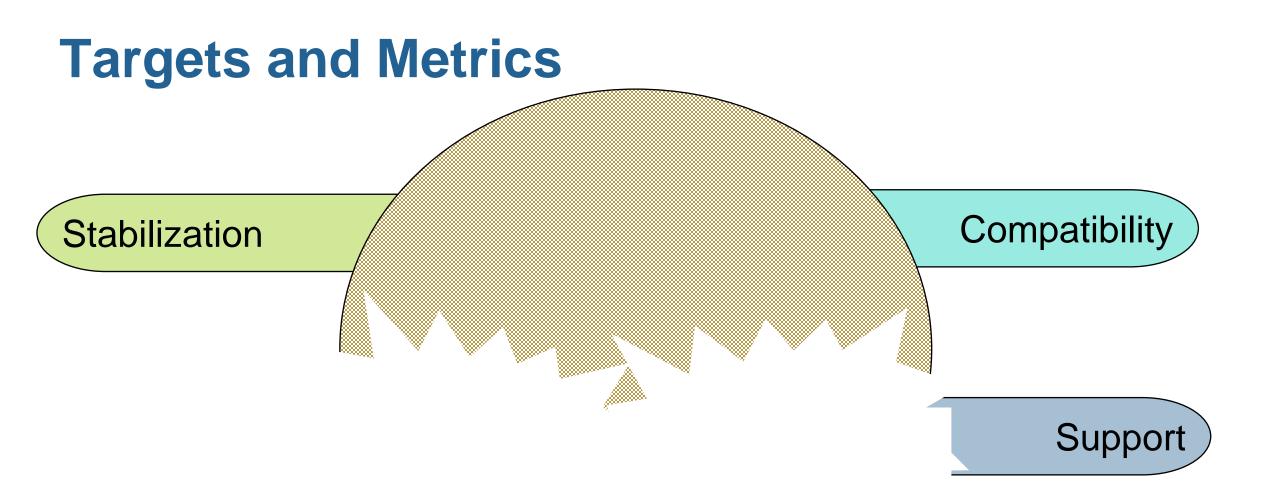


# **Compatibility Metrics**



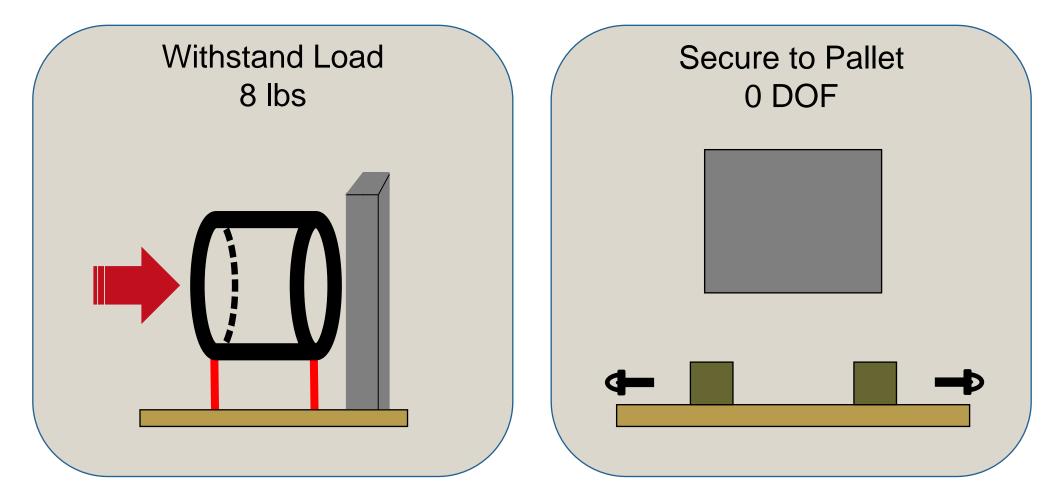
Segundo Sanchez





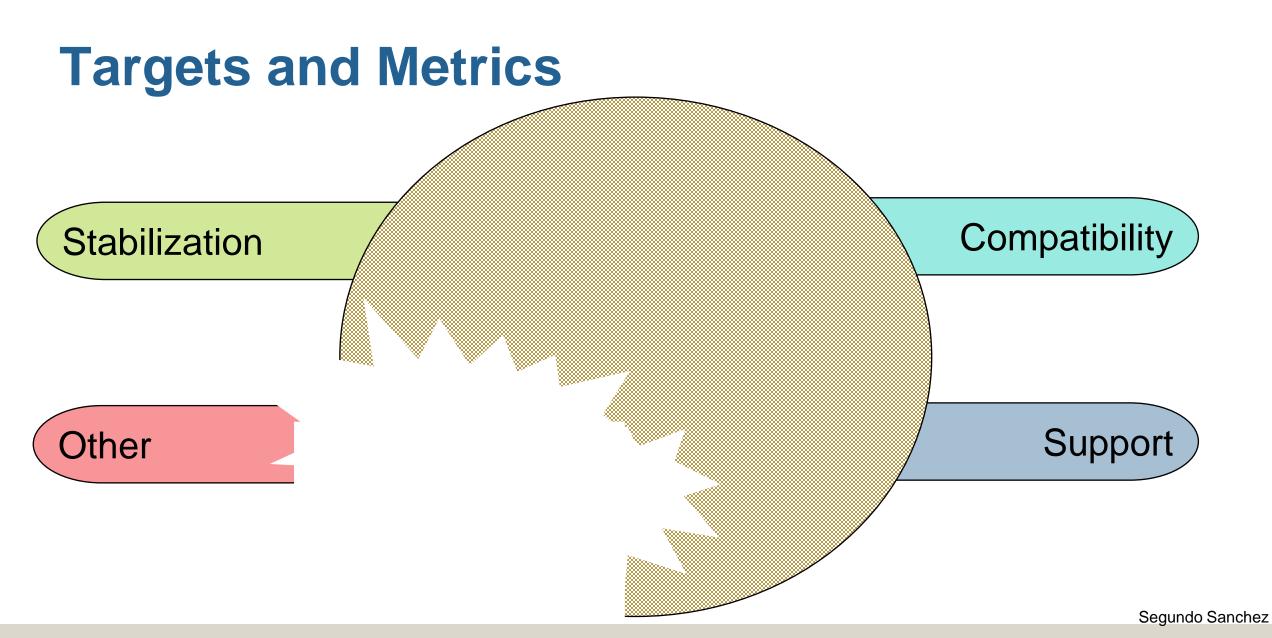


# **Support Metrics**



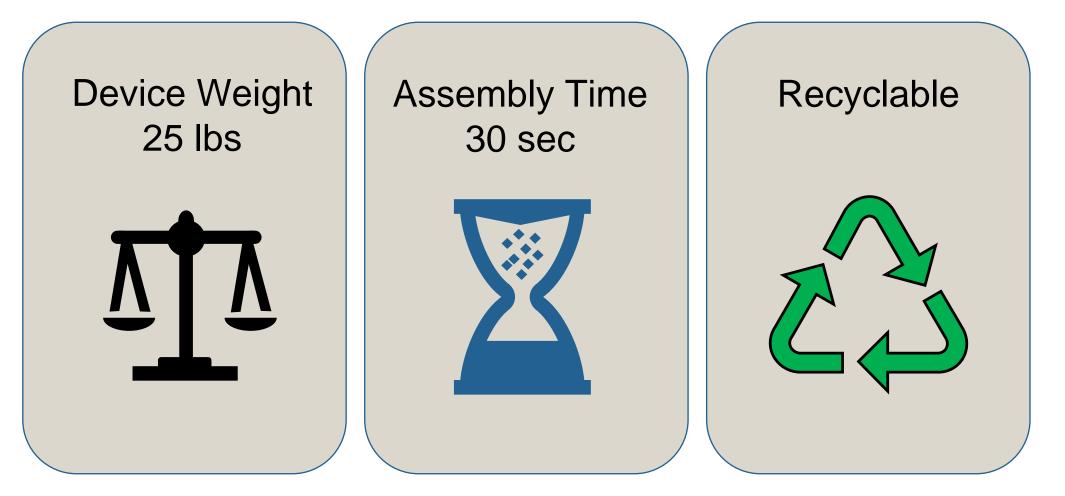
Segundo Sanchez







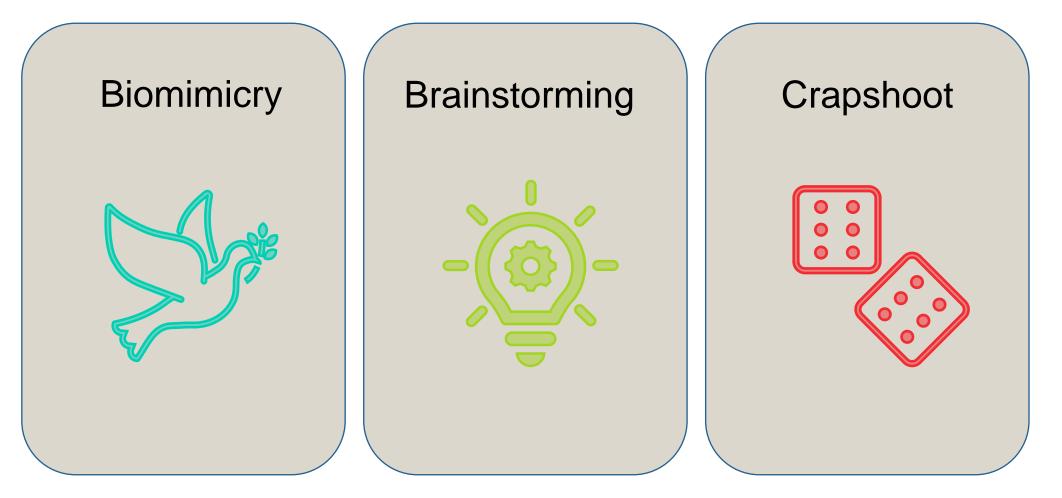
### **Other Metrics**



Segundo Sanchez

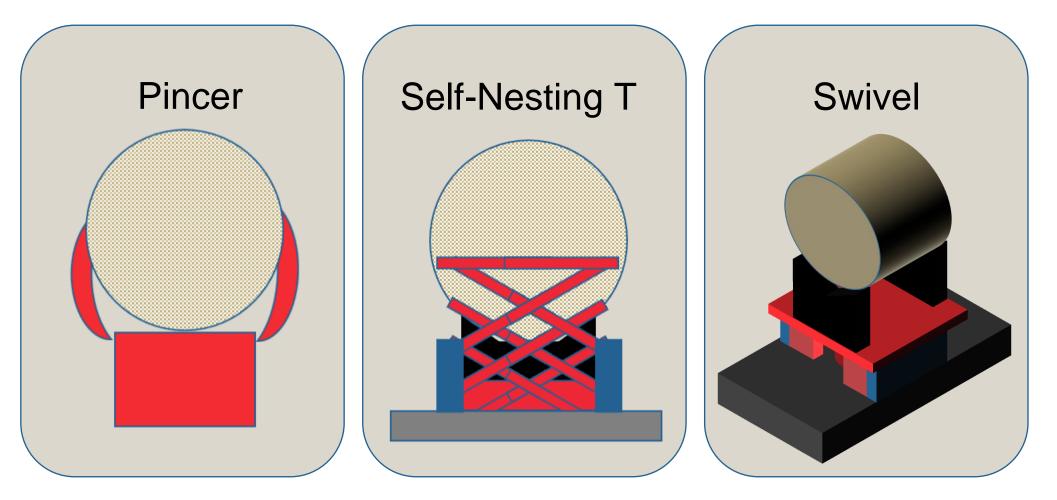


# **Concept Generation Tools**



Segundo Sanchez



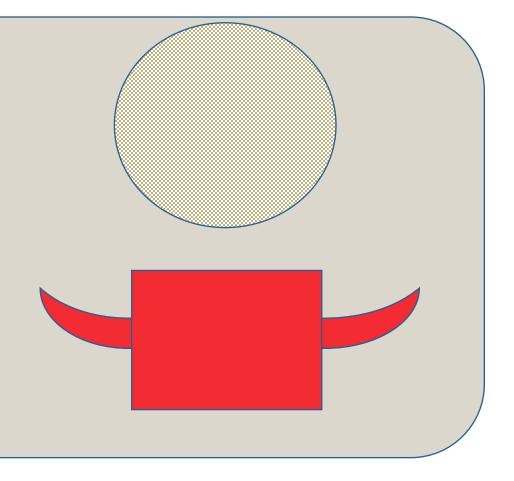


Segundo Sanchez



#### **Weight Activated Pincers**

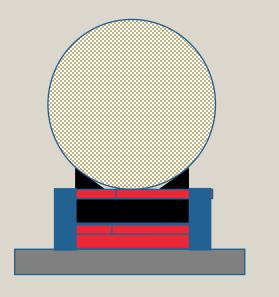
- Based on Corning's previous
  attempt
- When ceramic is placed on pincer, weight activates arms to hold ceramic in place
- Usable for any size ceramic





#### **Self-Nesting T**

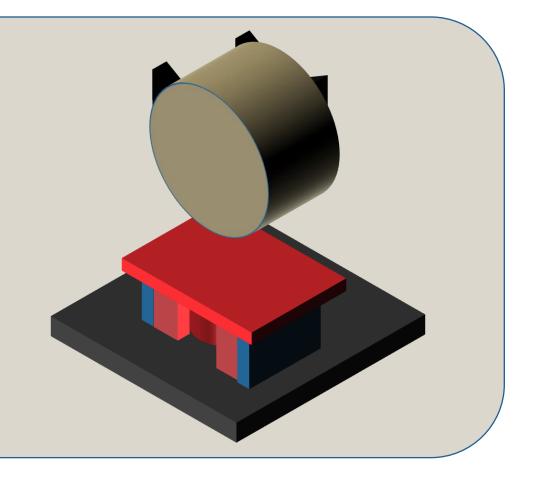
- Device has similar shape to Corning's current method
- Trigger activated and collapsible
- Uses mechanism on conveyor to activate





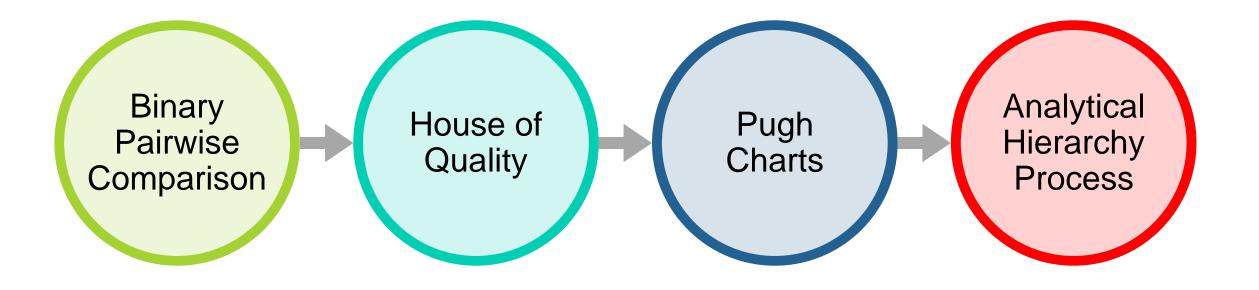
#### **Magnetic Locking Swivel**

- Swivel that locks using magnets
- Overhang on conveyor will rotate swivel
- Ceramics will never travel face first, eliminating tipping



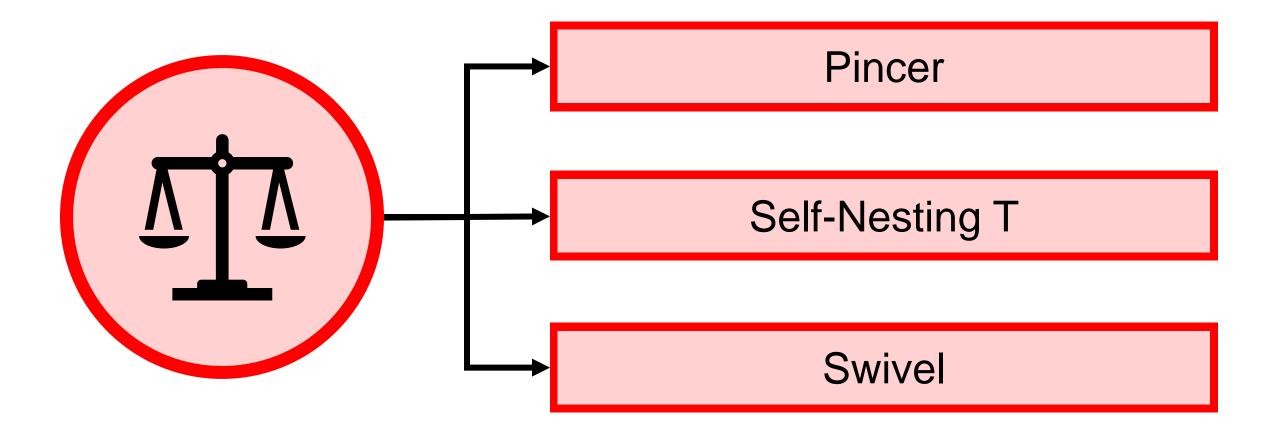


### **Concept Selection**





## **Analytical Hierarchy Process**



Segundo Sanchez

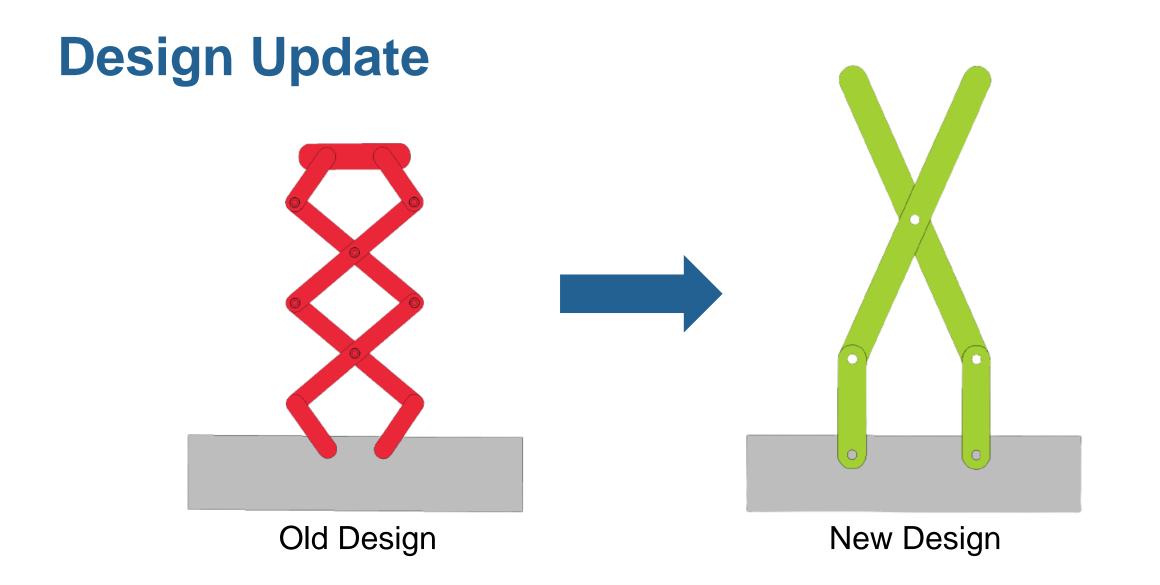


# **Final Selection**

- Similar to working design
- Trigger activated and collapsible
- Uses mechanism on conveyor to activate



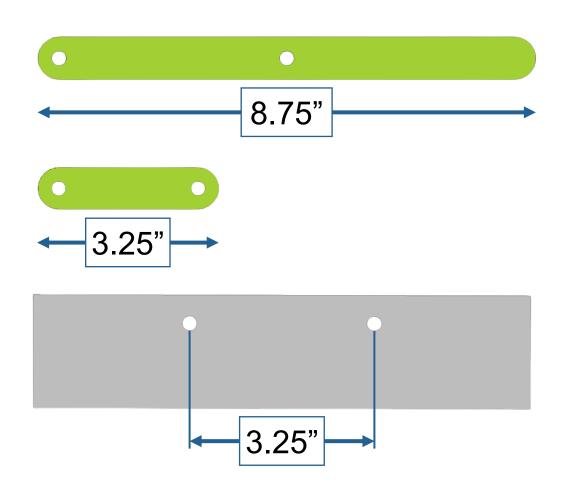


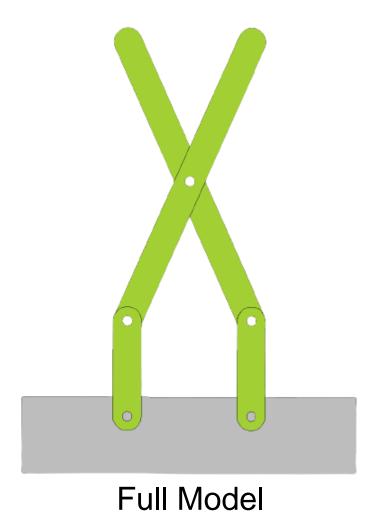


Robert Kosmas



### **Dimensions**

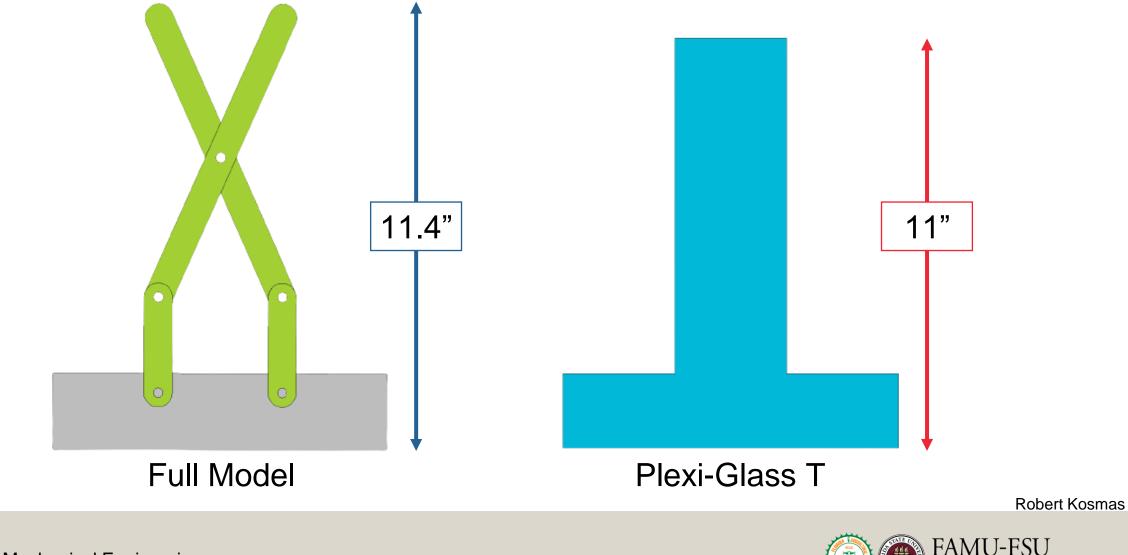




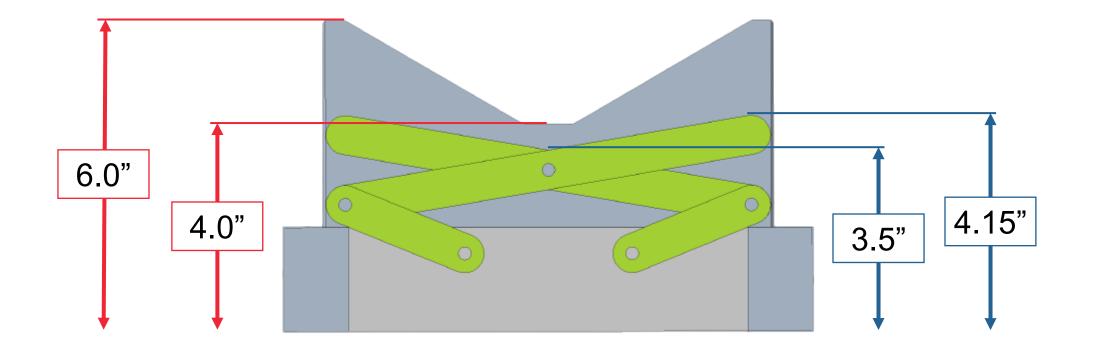
**Robert Kosmas** 



### **Dimensions**



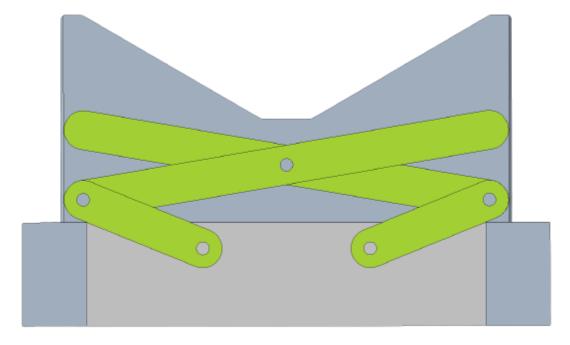
### **Vertical Retraction**

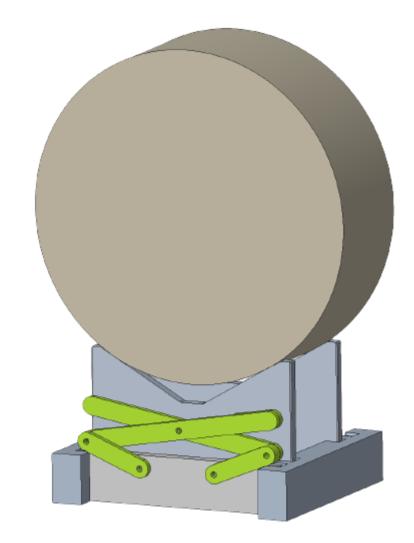


Robert Kosmas



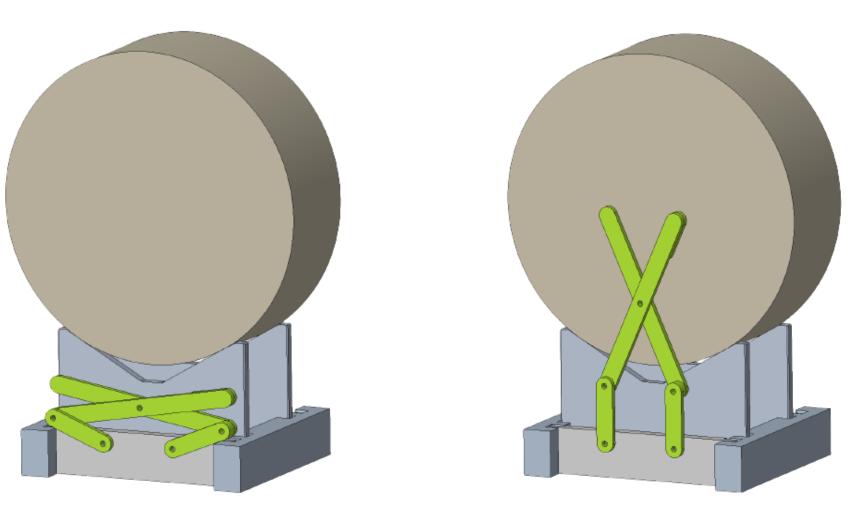
### **Vertical Retraction**





**Robert Kosmas** 



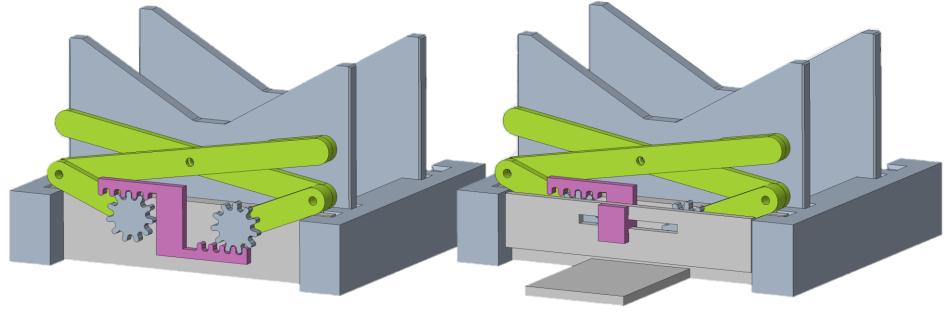


Robert Kosmas



#### **Gear and Rack Slider**

- "Z" shaped rack allows simultaneous rotation
- Will slide using a slot on the outer wall
- The outer wall will be raised for particle flow

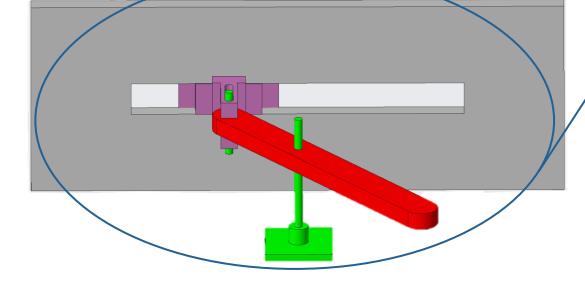


Robert Kosmas



#### **Slider Joint and Switch**

- The rack will act as a slider
- Slotted joint connection will allow for rotation of the switch



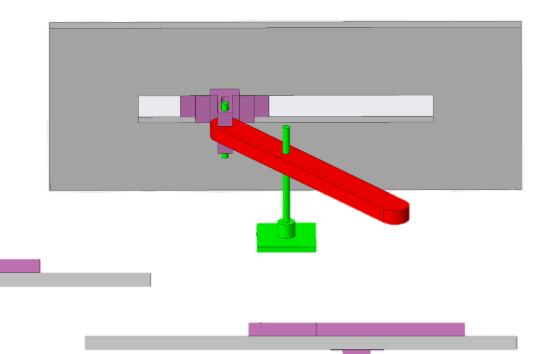
Robert Kosmas



RALAF

#### **Slider Joint and Switch**

- The rack will act as a slider
- Slotted joint connection will allow for rotation of the switch



Robert Kosmas



# **Current Challenges**

- Finalize connection from slide to switch bar
  Merge CAD's, correct positioning, check on the machinability of the connection
- Finalize self-nesting T CAD

Adjust tolerances, add hardware, communicate with machine shop for final adjustments

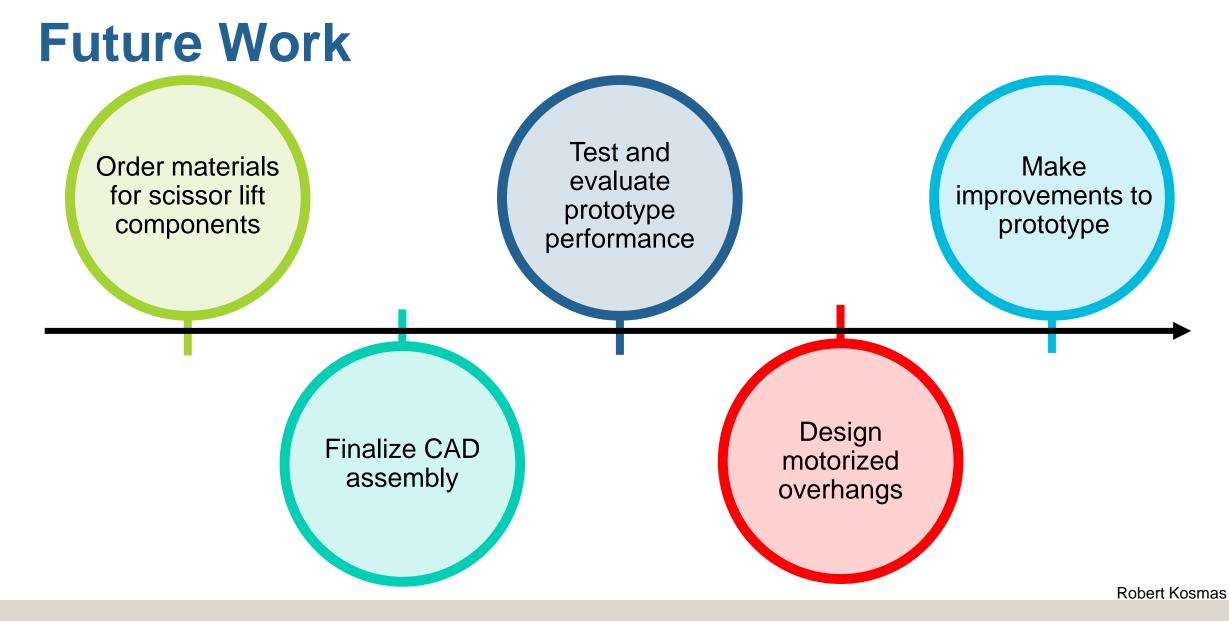
Developing motorized overhangs

Determine positioning, type of motors, and forces needed

Test mechanisms durability

□ Mobility during harsh conditions, impact resistance, material resistance







# Thank you!

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