



FAMU-FSU  
College of  
Engineering

# Virtual Design Review 5

## Team 505

Danfoss Stepper Motor Lifecycle Fixture

02/18/2025

# Team Introductions



**Bradford Andrews**  
Mechatronics  
Engineer



**Albert Auer**  
Mechanical Design  
Engineer

Presenter



**Chaney Bushman**  
Manufacturing and  
Test Engineer



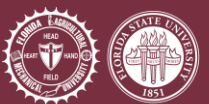
**Joseph Garvie**  
Systems Engineer

Presenter



**Mason Herbet**  
CAD Designer

Presenter



# Sponsor and Advisors



Sponsor  
Cole Gray  
*Senior Mechanical Design  
Engineer*



FAMU-FSU  
College of Engineering



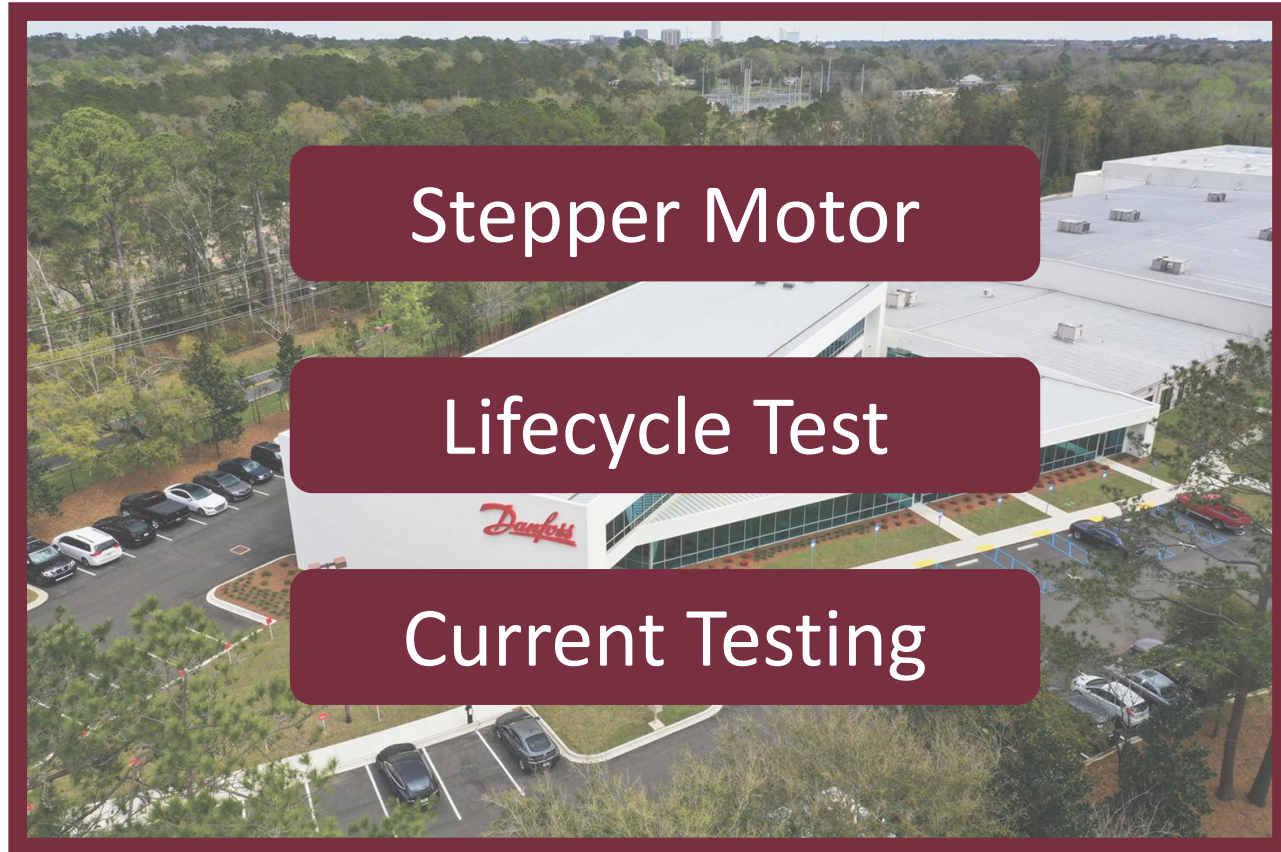
Academic Advisor  
Patrick Hollis, Ph.D.  
*Associate Professor &  
Undergraduate Coordinator*



Academic Advisor  
Shayne McConomy, Ph.D.  
*Senior Design Professor*

# Project Description

The objective of this project is to design and produce a **stepper motor lifecycle test** fixture for Danfoss Turbocor to improve user-friendliness and reliability over their **current testing** procedure.



## IGV Assembly

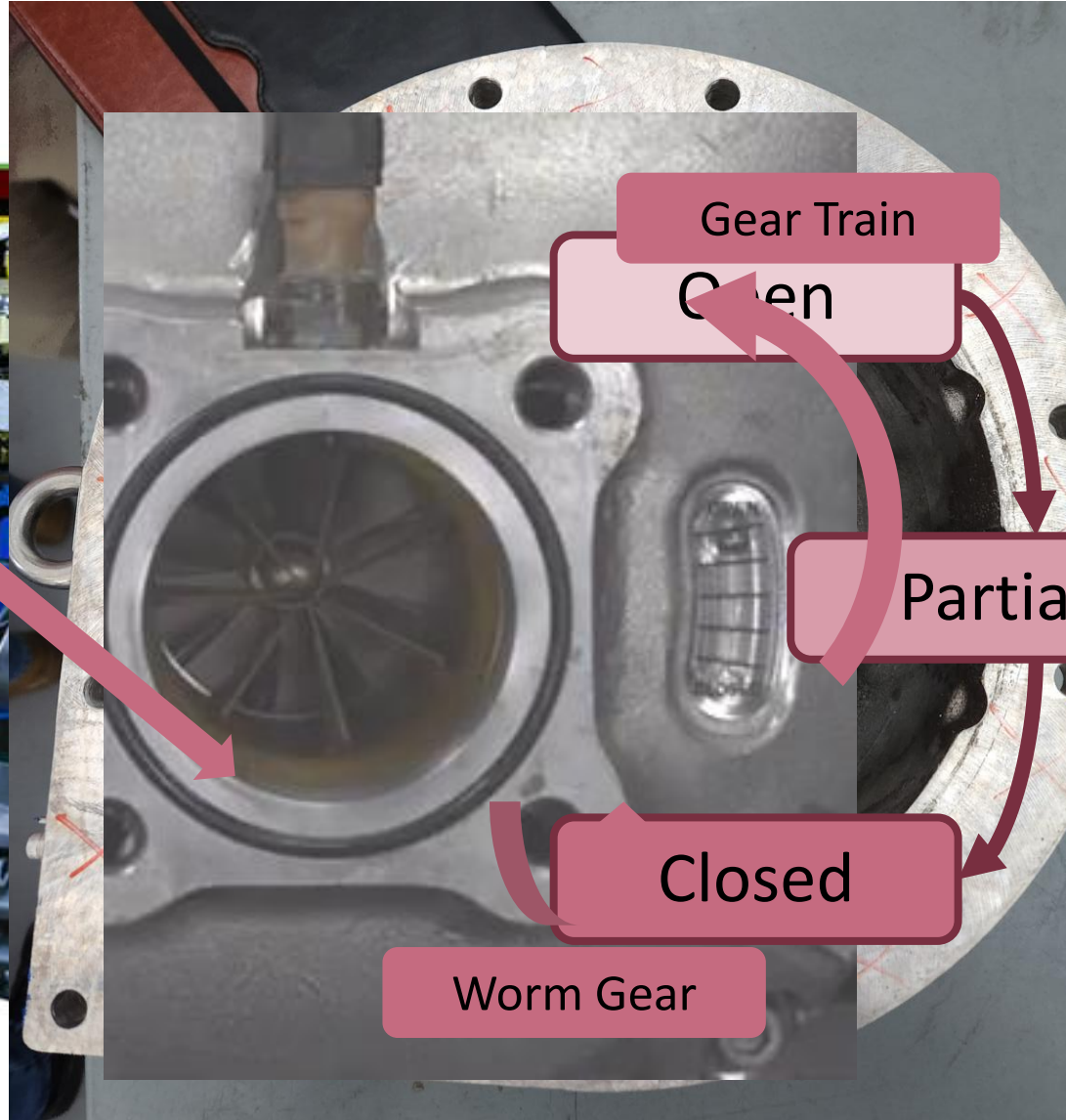
### 910098 Stepper Motor



Controls the fluid flow at the intake of the compressor



### Danfoss Turbo Cor TG Series



Gear Train

Open

Partial

Closed

Worm Gear

## What is it?

- A stepper motor lifecycle test aims to evaluate the expected lifespan and reliability of the motor under typical operating conditions.

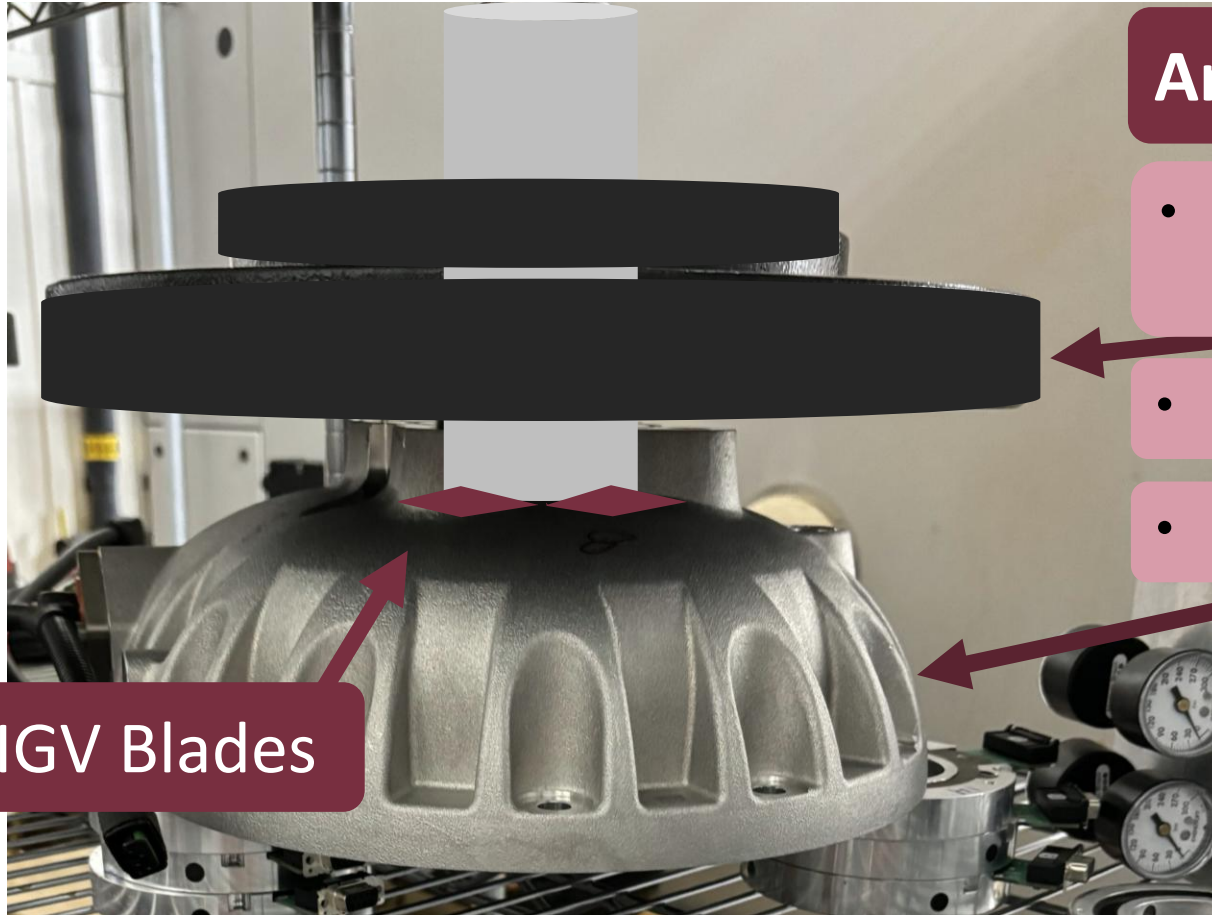
## Why does Danfoss use it?

- Quality control
- Customer Confidence
- Varied Motor Manufacturers

Proposed Lifecycle



Actual Lifecycle



### Areas of Improvement:

- Better representation of typical operating conditions

at various weight rates

- Add Human-Machine Interface (HMI)

- Automate Rotation Counting

### Assembly

IGV Blades



# Starting Point

## Perma-Tork



Uses permanent magnets to apply a constant torsional load to the central shaft

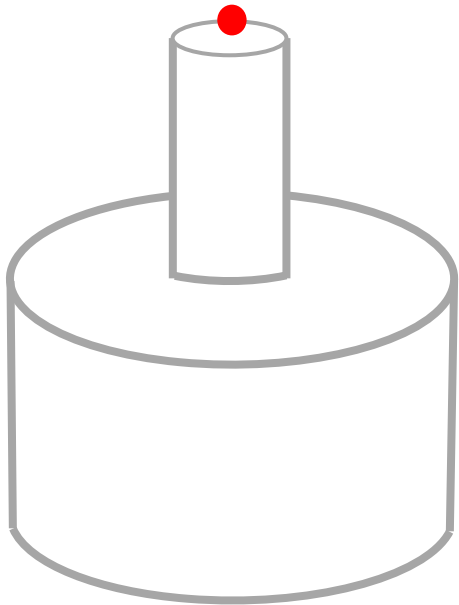
## Reasons to Use:

- Eliminates unnecessary friction
- Requires no power supply
- Allows manual torque adjustment



# Customer Needs

## One Direction Test

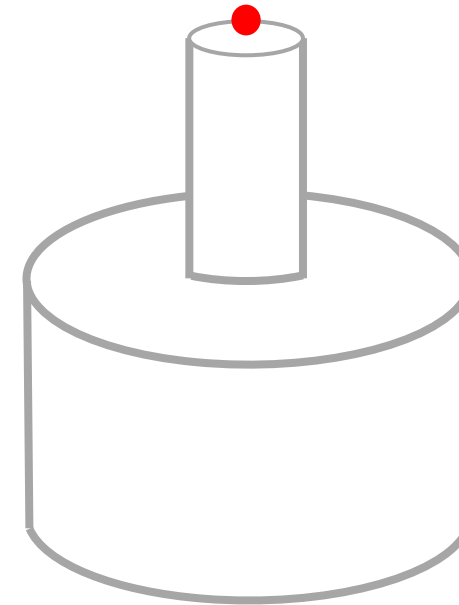


Runs continuously in one direction (CW CCW)

## Similarities

- Constant speed (pulses per second)
- Constant resistance torque (N-m)
- Run until failure (motor cannot rotate)
- Track total runtime and total rotations

## Alternating Test



Switches direction after a designated period of time (cycle time)

# Concept Selection

## Customer Needs

Motor is oriented downwards

## Assumptions

Standard 120V Outlet

Fixture housed on 16in wire shelf

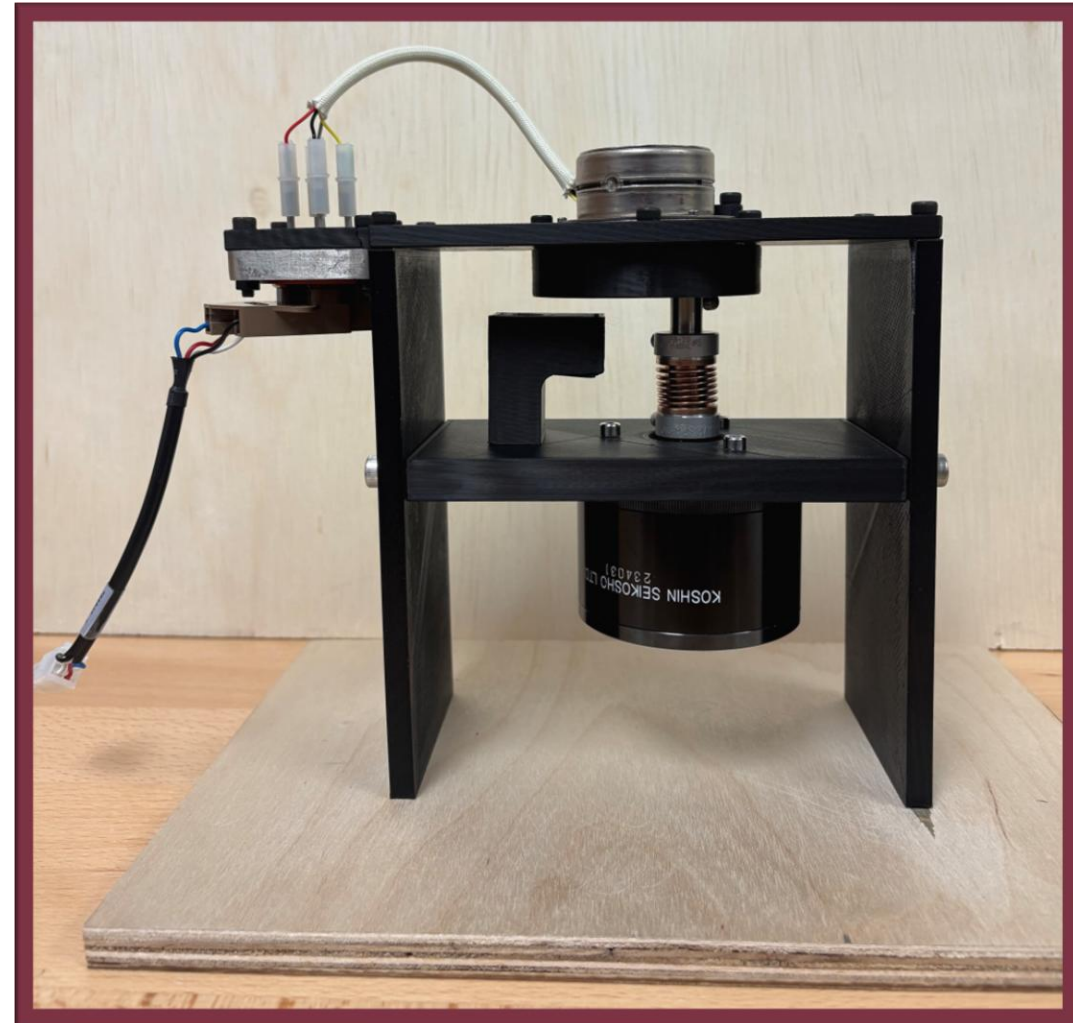
## Targets/Metrics

Adjust Cycle Time (0-300sec)

Adjust Speed (0-250pps)

Track Rotations (>98% Acc)

## H-Frame Prototype



# Concept Selection

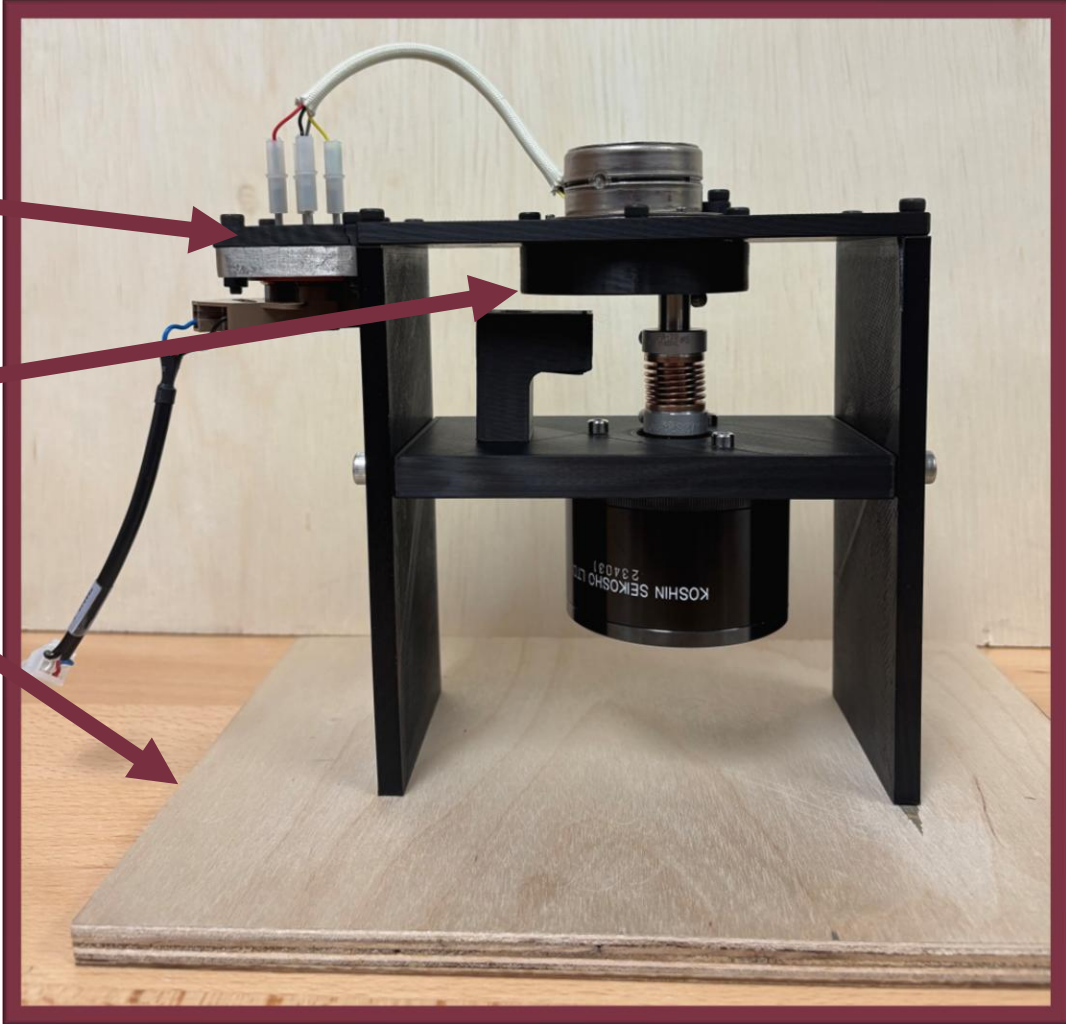
## H-Frame Prototype

### Prototype Improvements

Consolidation of stepper motor wiring to top plate

Design choices for easy CNC machining

Addition of baseplate to accommodate HMI



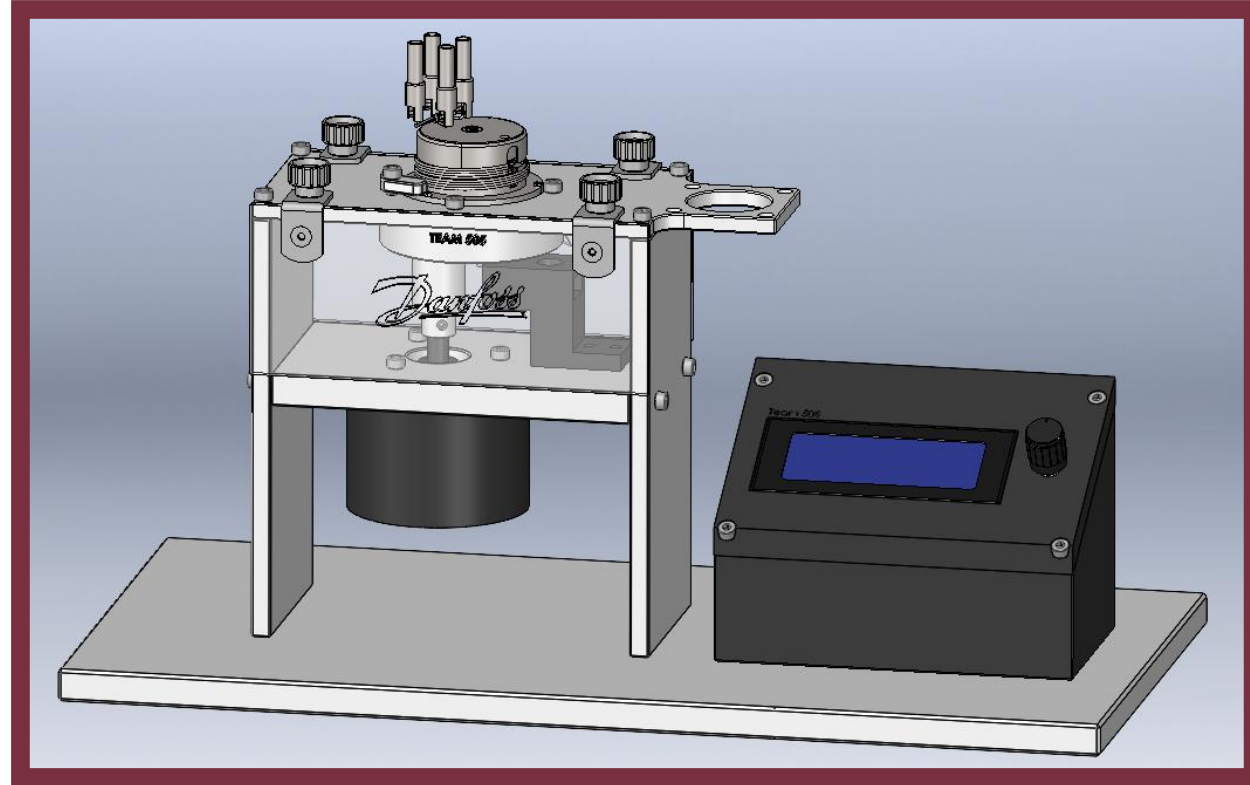
# Structure Design Changes

## Improvements

Plexiglass paneling

Aluminum Structure

Standardization of fasteners



# HMI Integration

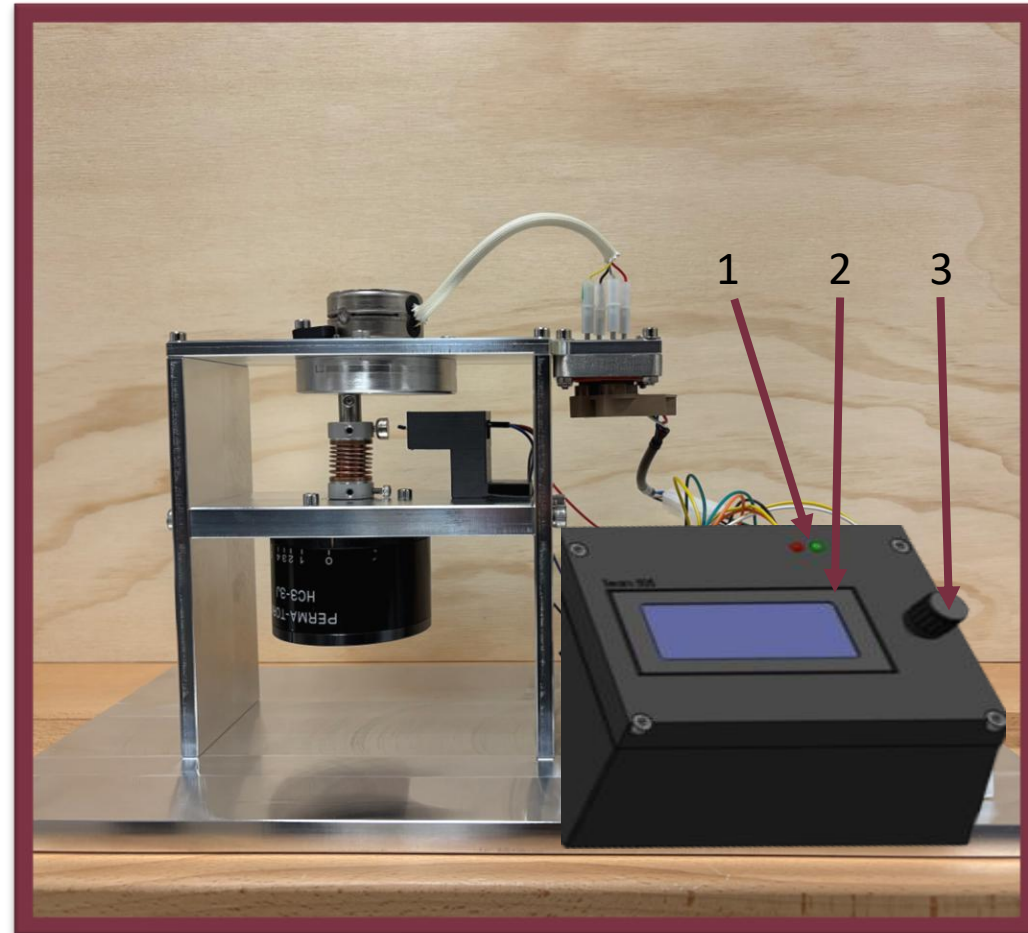
## Hardware Integration

- 1) Status LEDs
- 2) LCD Screen
- 3) Rotary Encoder

## Safety and compliance

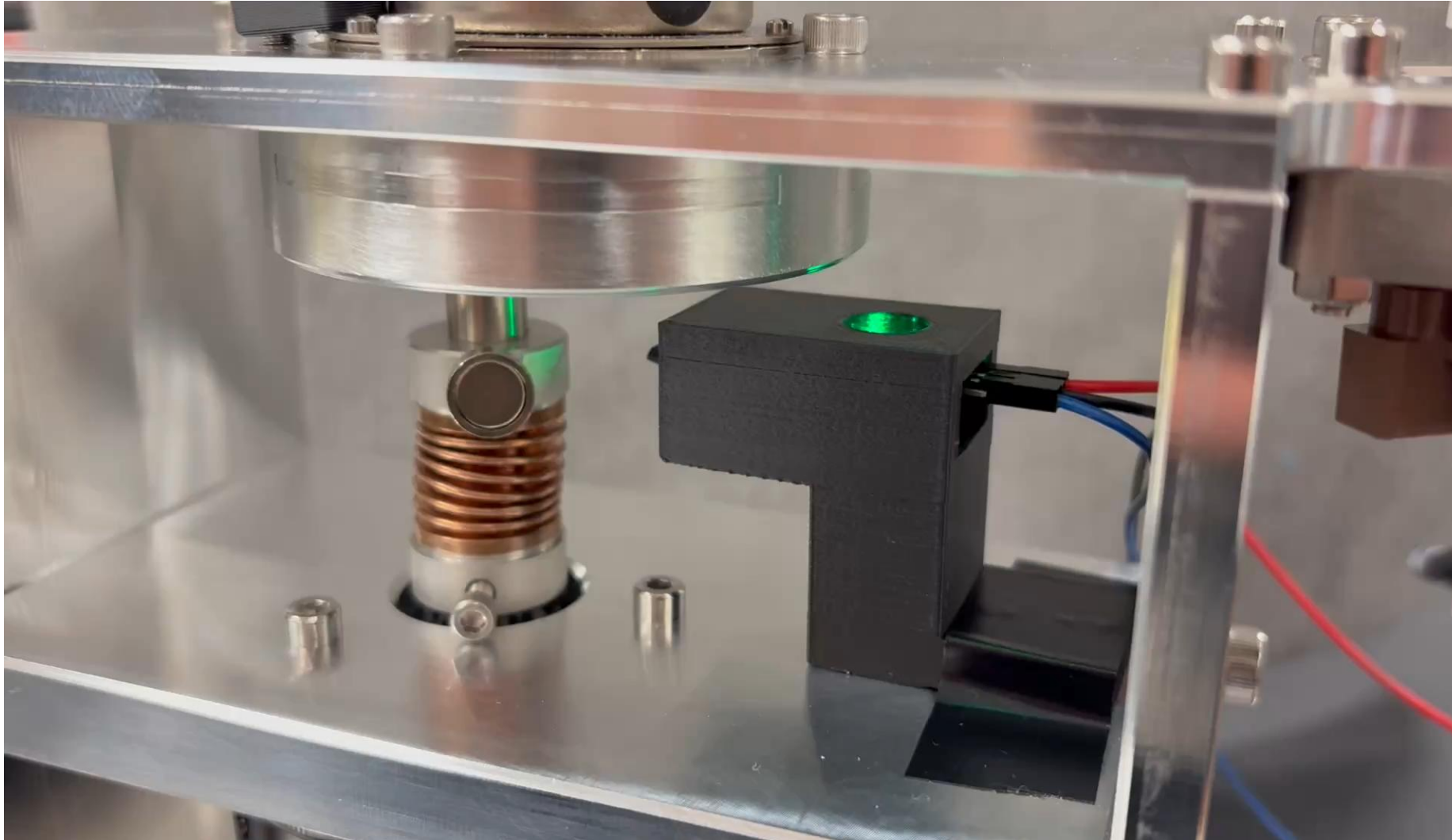
8-pin Molex Connector

Custom PCB



# Coupler with Fastened Magnet

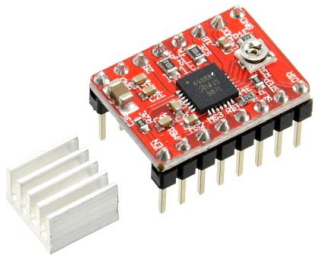
Albert Auer



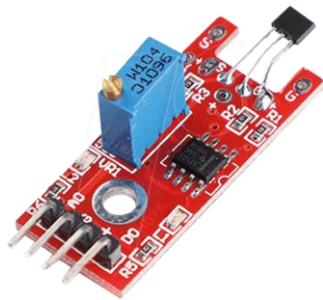
# Main Electronics



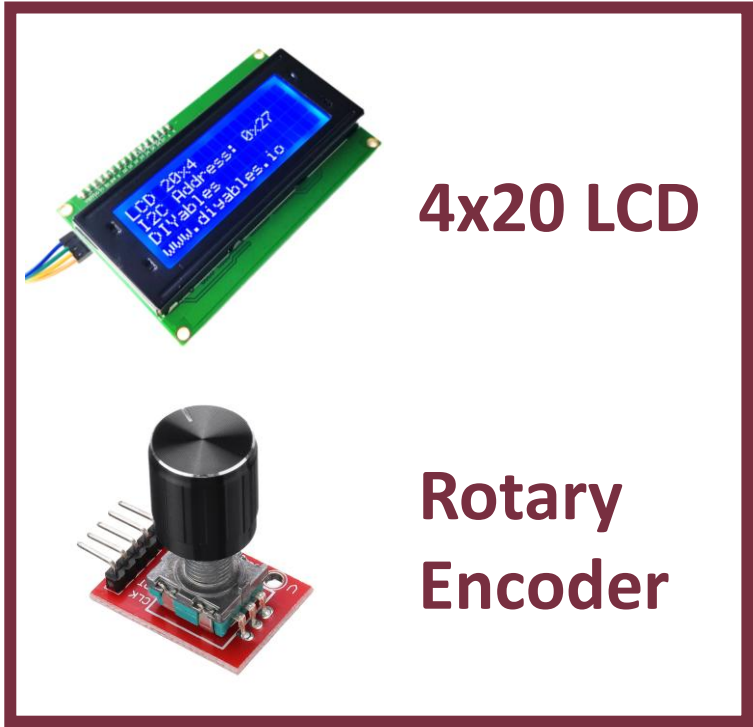
Arduino Uno



Stepper Motor Driver



Magnetic Sensor



4x20 LCD

Rotary Encoder

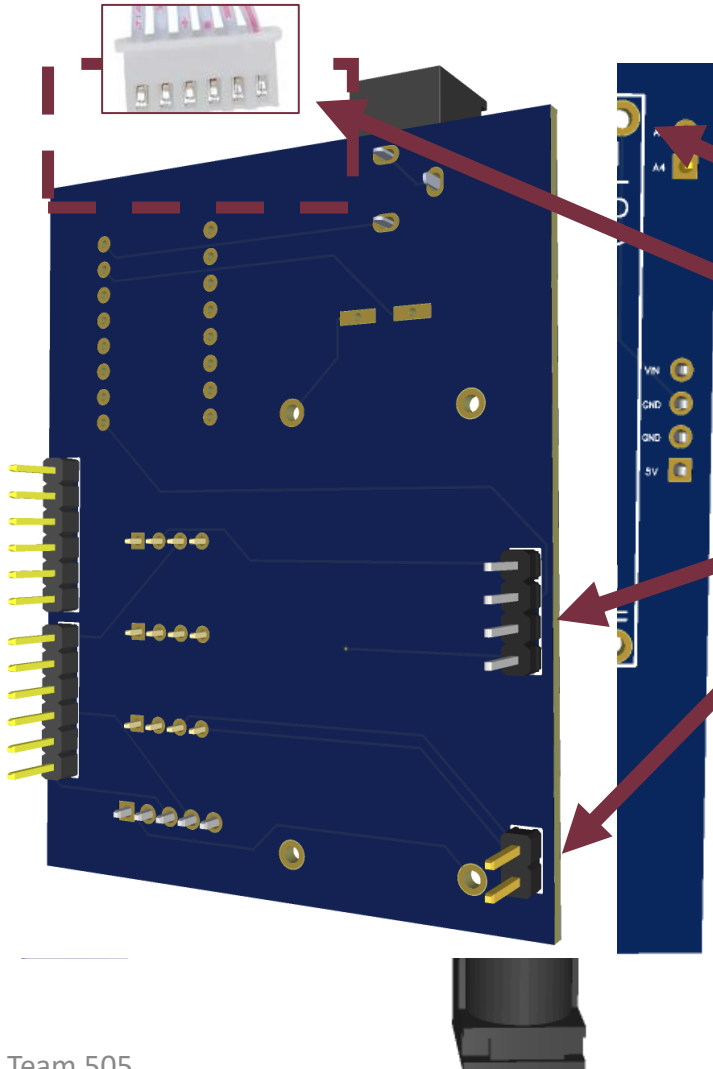
HMI



## Hardware

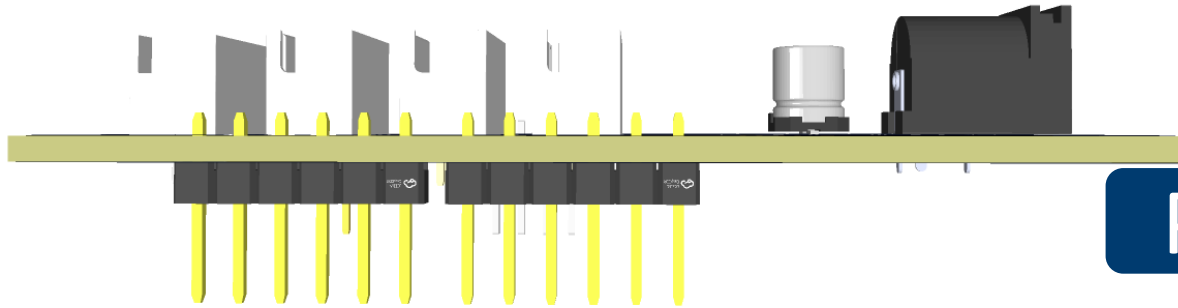
### Custom Printed Circuit Board (PCB)

- Two-Layer with mounting holes for each component
- Plug-in connectors for sensor and motor wiring
- Pins on PCB match corresponding pins on Arduino board





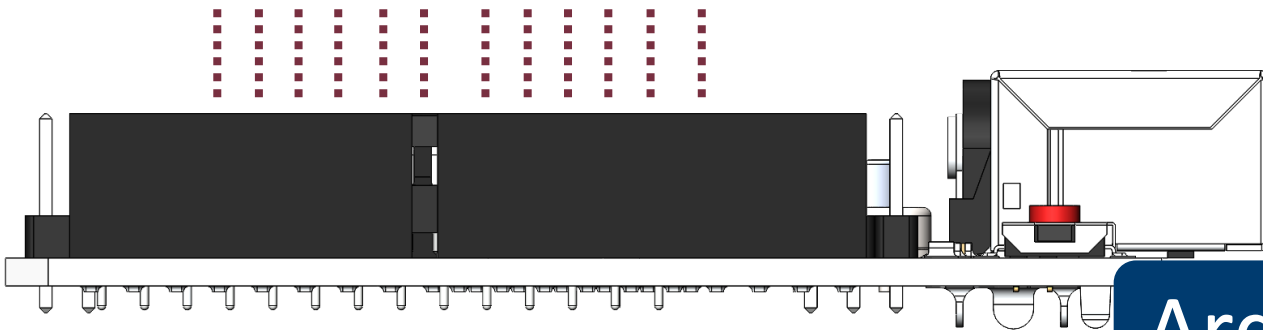
## Hardware



PCB

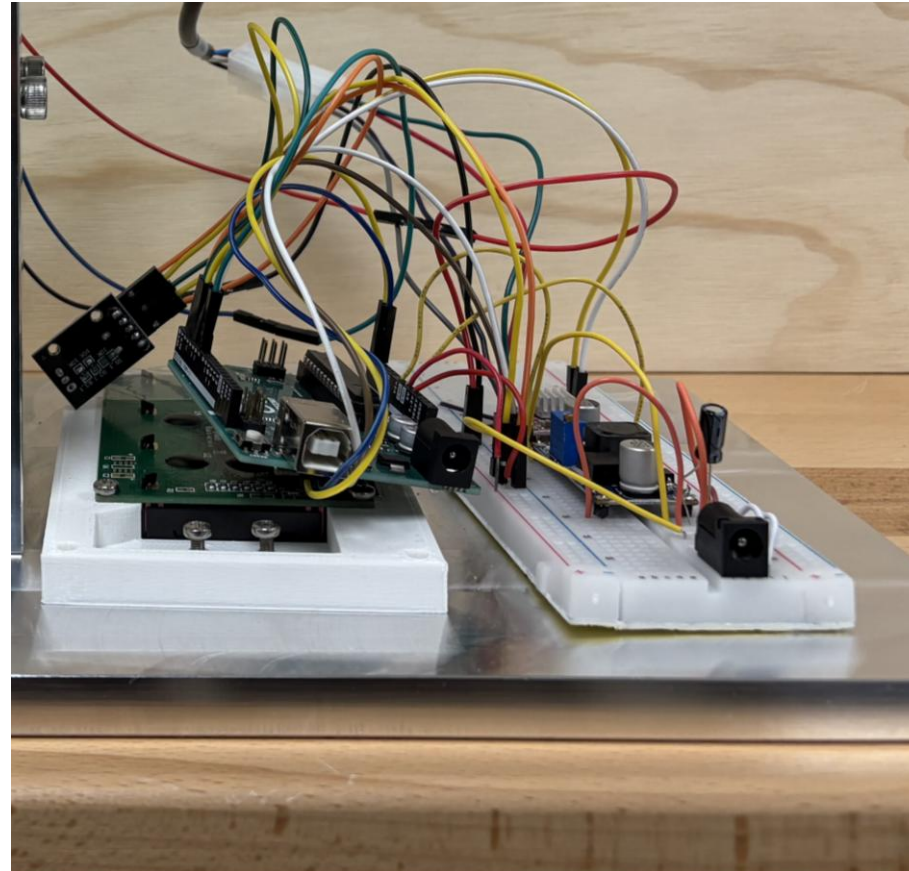
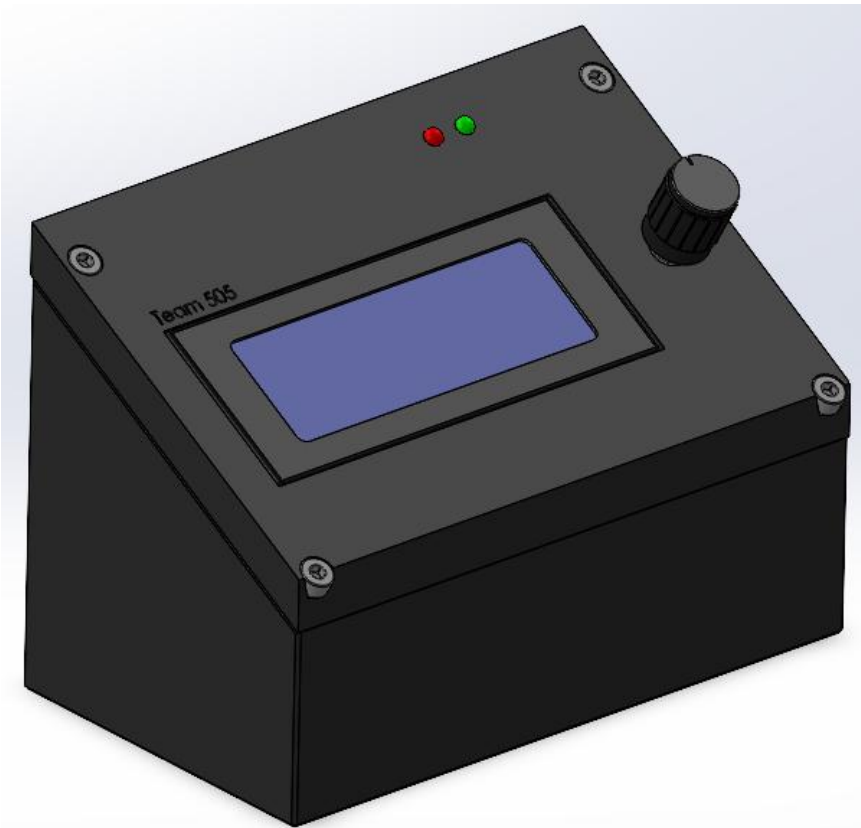
### Printed Circuit Board stacks above Arduino

- Significantly improves wire management
- Allows for electronics to be stored in tighter spaces
- Easy for Danfoss to reproduce and assemble

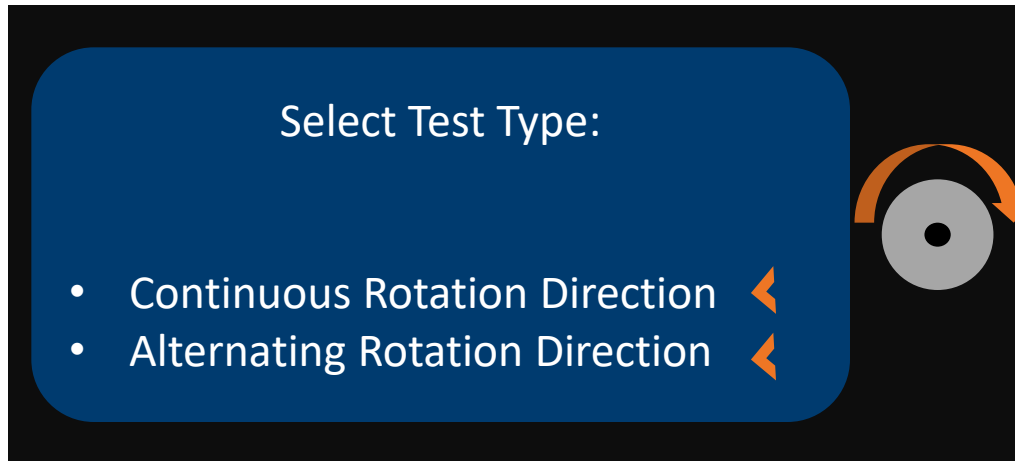


Arduino

# HMI User Interaction



## HMI User Interaction




### Screen Adjustment Knob

- Rotate to scroll through test parameters
- Push to confirm selection

## HMI User Interaction

Alternating Rotation Direction

- Speed
- Cycle Count\*



\*Represents the number of shaft rotations in one direction before switching to the opposite direction and repeating


## HMI User Interaction

Continuous Rotation Direction

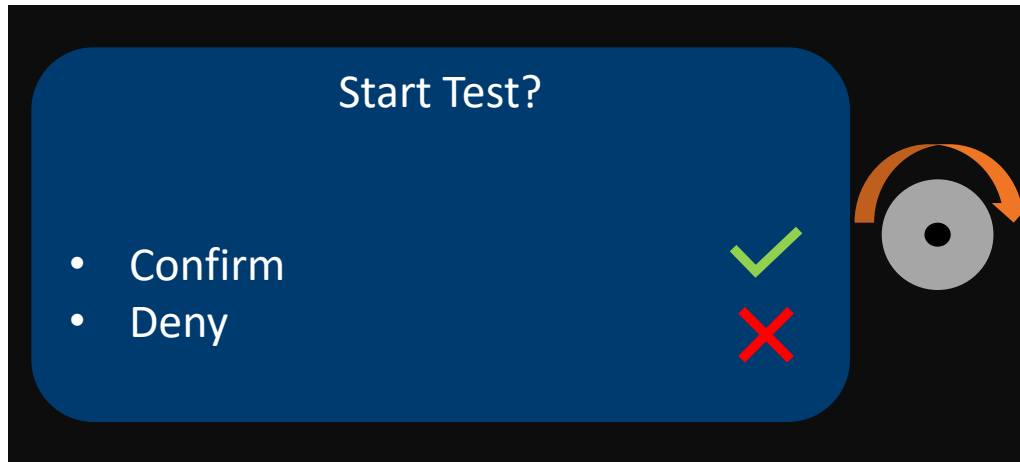
- Speed
- Direction

# PPS

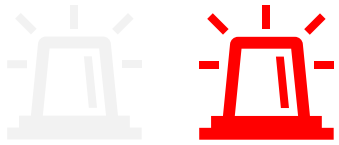
CW/CCW

A diagram of a motor with a grey circular body and a black center. An orange arrow curves around the top of the motor, pointing to the right, indicating clockwise rotation.

## HMI User Interaction



## HMI User Interaction



Post Test Results

- Total Runtime
- Rotations

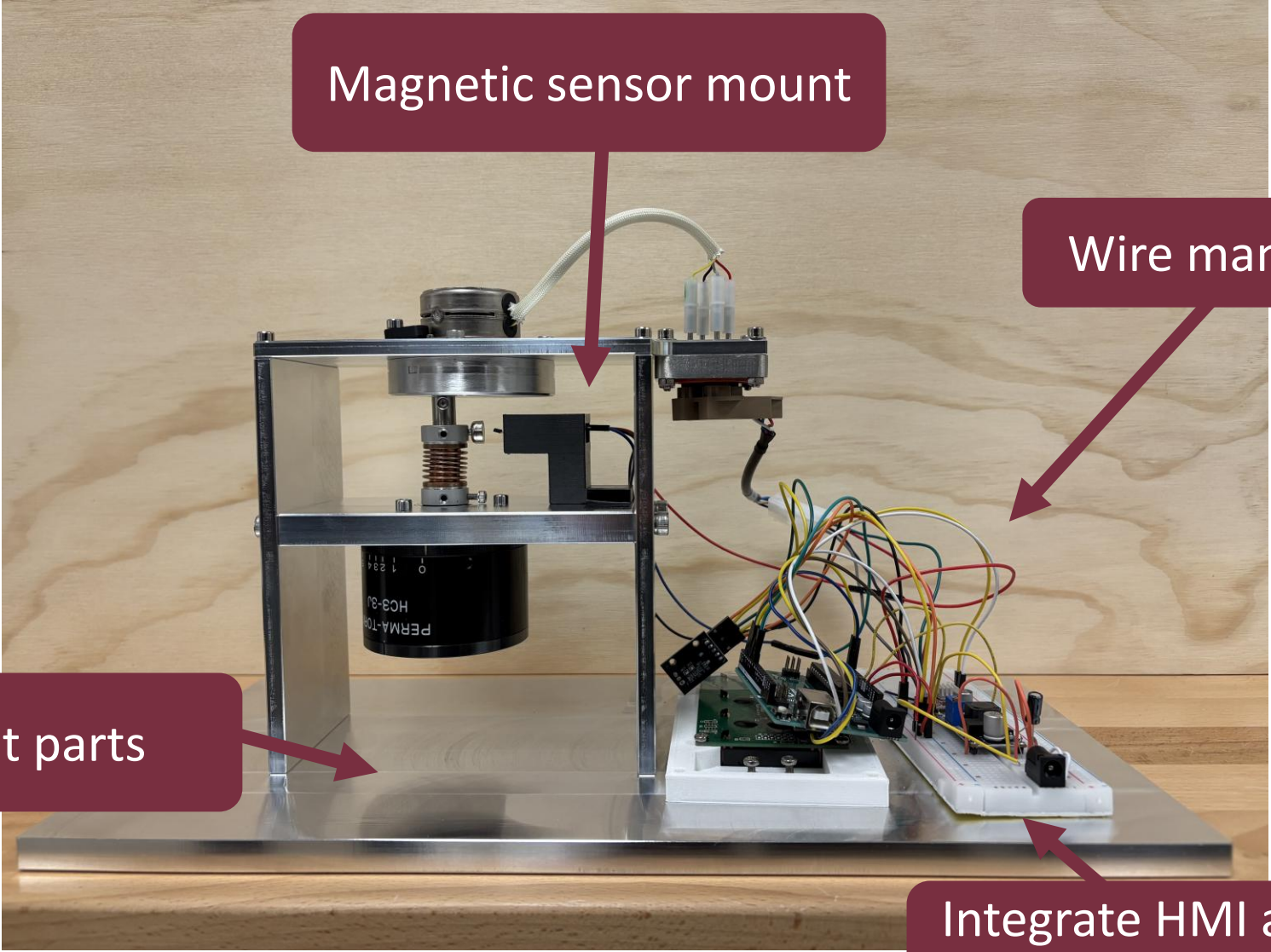
Day : Hr : Min

# rotations

### HMI Display & Test Status

- Display test results on LCD screen
- Red/green LEDs indicate test completion status (motor failure)

# Future Improvements



Magnetic sensor mount

Wire management

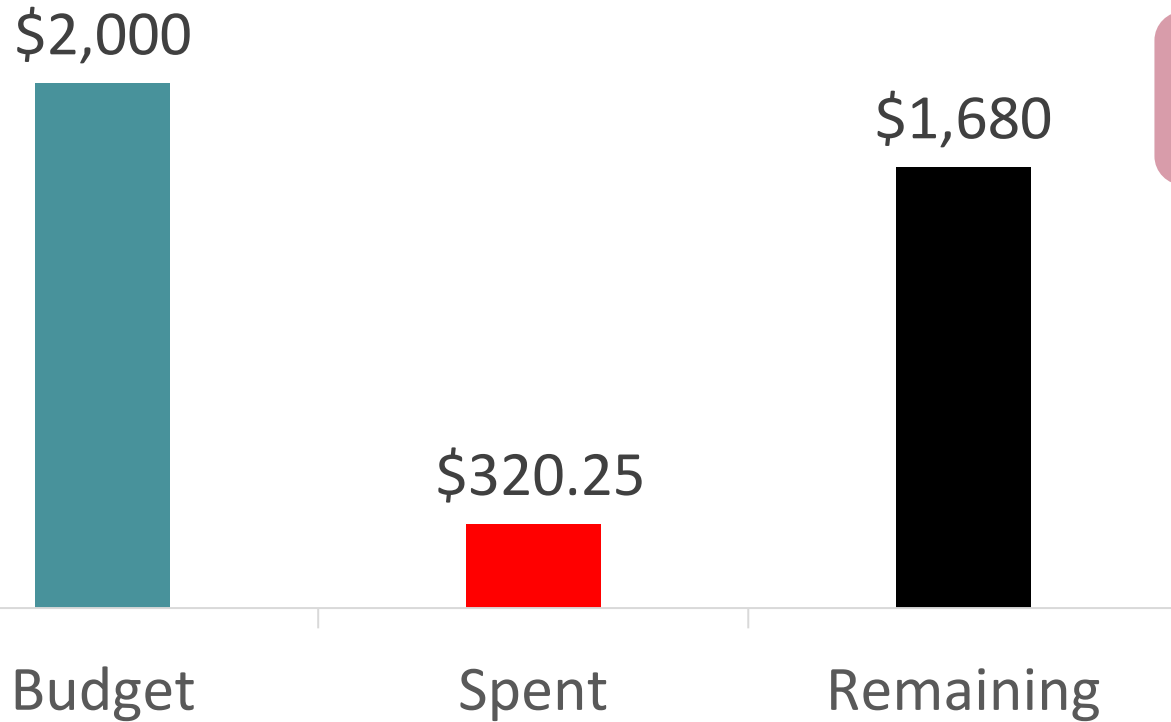
Powder coat parts

Integrate HMI assembly into fixture



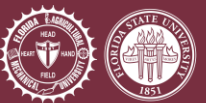


# Updated Budget

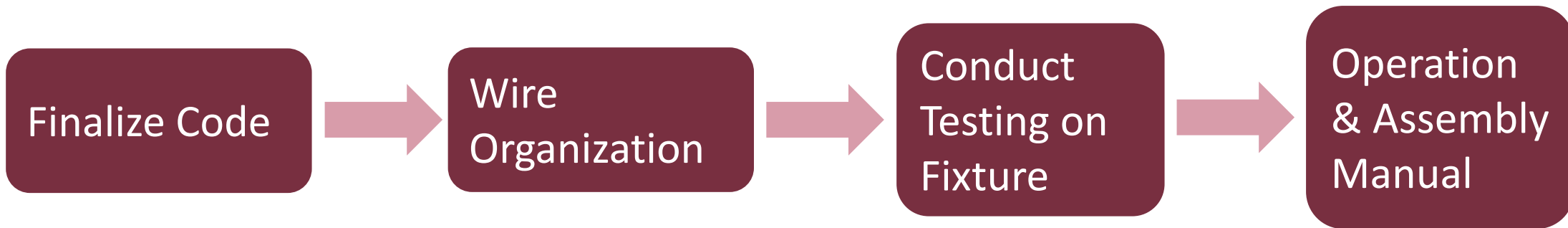


## Expected Future Costs

- Printed Circuit Board
- Powder coat machined parts



# Future Work



# Questions?

