Introduction

Multiple integrals:

• Areas (cost, ...):

 $dA = dx \, dy \qquad dA = \rho \, d\rho \, d\theta$

• Volumes (weight, ...):

 $\mathrm{d} V = \,\mathrm{d} x\,\mathrm{d} y\,\mathrm{d} z \qquad \mathrm{d} V = \rho\,\mathrm{d} \rho\,\mathrm{d} \theta\,\mathrm{d} z \qquad \mathrm{d} V = r^2\sin\phi\,\mathrm{d} r\,\mathrm{d} \phi\,\mathrm{d} \theta$

• Centroids (center of gravity, center of pressure, ...)

$$\bar{x} = \int x \, \mathrm{d}A / \int \mathrm{d}A \qquad \bar{x} = \int x \, \mathrm{d}V / \int \mathrm{d}V$$

• Moments of inertia (solid body dynamics, center of pressure, ...)

$$I_x = \int y^2 \, \mathrm{d}A \qquad I_0 = \int x^2 + y^2 \, \mathrm{d}A$$
$$I_x = \int y^2 + z^2 \, \mathrm{d}V \qquad I_{xy} = -\int xy \, \mathrm{d}V$$

• ...

Notes:

- Draw the region to be integrated over.
- When integrating, say $\int \int \int f(a, b, c) da db dc$, you have to decide whether you want to do a, b, or c first.
- Usually, you do the coordinate with the easiest limits of integration first.
- If you decide to do, say, b first, $(\int_{b_1}^{b_2} f(a, b, c) db$ first), the limits of integration b_1 and b_2 must be identified from the graph at *arbitrary* a and c, and are normally functions of a and c: $b_1 = b_1(a, c), b_2 = b_2(a, c)$.
- After integrating over, say, b, the remaining double integral should no longer depend on b in any way. Nor does the region of integration: redraw it without the b coordinate. Then integrate over the next easiest coordinate in the same way.