

# Introduction

Eigenvalues:

- buckling;
- modes of vibration;
- dynamical systems;
- principal axes;
- boundary layer instability;
- heat conduction;
- acoustics;
- electrical circuits;
- stability of numerical methods;
- exam questions;
- ...

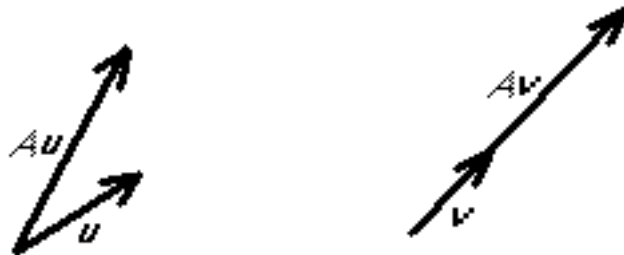
*Definition*

A nonzero vector  $\vec{v}$  is an eigenvector of a matrix  $A$  if  $A\vec{v}$  is a multiple of  $\vec{v}$ :

$$A\vec{v} = \lambda\vec{v}$$

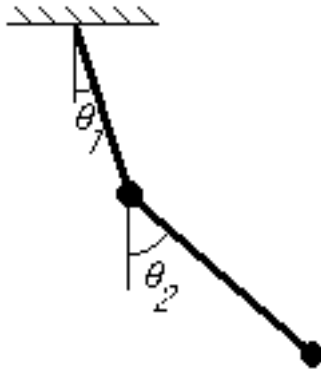
The number  $\lambda$  is called the corresponding eigenvalue.

Graphically, if  $\vec{v}$  is an eigenvector of  $A$ , then the vector  $A\vec{v}$  is in the same (or exactly opposite direction) as  $\vec{v}$ :



An eigenvector is indeterminate by a constant that must be chosen.

*Example*



Equations of motion:

$$M \begin{pmatrix} \ddot{\theta}_1 \\ \ddot{\theta}_2 \end{pmatrix} + K \begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix} = 0$$

Setting  $\vec{\theta} \equiv (\theta_1, \theta_2)$

$$M\ddot{\vec{\theta}} + K\vec{\theta} = 0$$

Premultiplying by  $M^{-1}$  and defining  $A = M^{-1}K$ ,

$$\ddot{\vec{\theta}} + A\vec{\theta} = 0$$

Try solutions of the form  $\vec{\theta} = \vec{C}e^{i\omega t}$ . The constant vector  $\vec{C}$  determines the “mode shape:”  $\theta_1/\theta_2 = C_1/C_2$ . The exponential gives the time-dependent amplitude of this mode shape, with  $\omega$  the natural frequency.

Plugging the assumed solution into the equations of motion:

$$-\omega^2\vec{C} + A\vec{C} = 0 \quad \implies \quad A\vec{C} = \omega^2\vec{C}$$

So the mode shape  $\vec{C}$  is an eigenvector of  $A$  and the corresponding eigenvalue gives the square of the frequency.

There will be two different eigenvectors  $\vec{C}$ , hence two mode shapes and two corresponding frequencies.

Note: we may lose symmetry in the above procedure. There are better ways to do this.

*Procedure*

To find the eigenvalues and eigenvectors of a matrix  $A$ ,

1. Find the zeros of the determinant  $|A - \lambda I|$  (i.e. of matrix  $A$  with  $-\lambda$  added to each main diagonal element.) (The book uses  $\lambda I - A$ . This is very error-prone, and I do not recommend it.) For an  $n \times n$  matrix  $A$ ,  $|A - \lambda I|$  is an  $n$ -th degree polynomial in  $\lambda$ . From it, we can find  $n$  eigenvalues  $\lambda_1, \lambda_2, \dots, \lambda_n$ , (which do not all need to be distinct, however.)
2. When the eigenvalues are found, for each eigenvalue  $\lambda_i$  the corresponding eigenvector(s) can be found as the basis of the null space of  $A - \lambda_i I$ . *Note: Do not leave undetermined coefficients in eigenvectors. This is counted as an error.*