## Quadratic Forms

Examples:

- quadratic curves (circles, ellipses, hyperbolae, parabolae) and surfaces (spheres, spheroids, ellipsoids, cones, cylinders, ...);
- kinetic energy of solid bodies;
- potential energy near equilibria;
- ...

Matrix form:

$$
\begin{aligned}
\vec{x}^{T} A \vec{x} & =a_{11} x_{1}^{2}+a_{12} x_{1} x_{2}+a_{13} x_{1} x_{3}+\ldots \\
& +a_{21} x_{2} x_{1}+a_{22} x_{2}^{2}+a_{23} x_{2} x_{3}+\ldots \\
& +\ldots
\end{aligned}
$$

An orthonormal transformation leaves the quadratic form unchanged

$$
\vec{x}^{T} A^{\prime} \vec{x}^{\prime}=\vec{x}^{T} P^{T^{T}} P^{T} A P P^{T} \vec{x}=\vec{x}^{T} A \vec{x}
$$

but can simplify the coefficients. On principal axes

$$
\vec{x}^{T} A^{\prime} \vec{x}^{\prime}=a_{11}^{\prime} x_{1}^{\prime 2}+a_{22}^{\prime} x_{2}^{\prime 2}+\ldots
$$

